

# Linear Algebra II Lecture 3

$$F: \mathbb{R}^{2 \times 2} \rightarrow \mathbb{R}^2$$

is linear

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix} \mapsto \begin{pmatrix} a \\ d \end{pmatrix}$$

$$\text{Ker}(F) = \text{span} \left\{ \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} \right\}, \quad \dim(\text{Ker}(F)) = 2$$

$$\text{im}(F) = \mathbb{R}^2 \quad \dim(\text{im}(F)) = 2$$

$$\dim \mathbb{R}^{2 \times 2} = 4 = 2 + 2$$

Theorem 15.3 Let  $V$  be fin. gen. and let

$F: V \rightarrow W$  be a linear map. Then

$$\dim V = \underbrace{\dim(\text{Ker}(F))}_l + \underbrace{\dim(\text{im}(F))}_n$$

Proof sketch: •  $\text{Ker}(F) \subset V$  subspace, i.e.  $\text{Ker}(F)$  is fin. gen.

Let  $(v_1, \dots, v_l)$  be a basis of  $\text{Ker}(F)$ .

- We can extend this to a basis  $(v_1, \dots, v_l, u_1, \dots, u_n)$  of  $V$ . (Thm. 14.8)
- Show:  $(F(u_1), \dots, F(u_n))$  is a basis of  $\text{im}(F)$ .  
(Think about that!)

Example 51 Consider the linear map

$$D: P_2 \rightarrow P_2$$
$$f \mapsto f'$$

$$f(x) = ax^2 + bx + c, \quad Df(x) = 2ax + b$$

$$\text{Ker}(D) = P_0, \quad \text{im}(D) = P_1$$

$$\dim P_n = n+1, \quad B = (1, x, \dots, x^n)$$

will later show that this is a basis  
for arbitrary  $n$  (Vandermonde  
determinant)

Notice:  $P_n$  behaves like  $\mathbb{R}^{n+1}$  " $P_n$  and  
 $\mathbb{R}^{n+1}$  are isomorphic"

$$ax^2 + bx + c \rightsquigarrow \begin{pmatrix} a \\ b \\ c \end{pmatrix}$$

Above linear map can be described as a lin.  
map  $\mathbb{R}^3 \rightarrow \mathbb{R}^3$

$$\begin{pmatrix} a \\ b \\ c \end{pmatrix} \mapsto \begin{pmatrix} 0 \\ 2a \\ b \end{pmatrix} = \begin{pmatrix} 0 & 0 & 0 \\ 2 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix}$$

We will make this precise in the following:

Definition 15.4 i) (Recall) A fct.  $f: X \rightarrow Y$  is invertible if there exists a fct.  $g: Y \rightarrow X$  with  $f \circ g = \text{id}_Y$  and  $g \circ f = \text{id}_X$ .  $f$  is invertible iff  $f$  is bijective.

(ii) An invertible lin. map  $F: V \rightarrow W$  is called an isomorphism. (isos = equal, morphe = form / shape)

(iii) Two vector spaces  $V$  and  $W$  are called isomorphic (Notation  $V \cong W$ ) if there exists an isomorphism  $F: V \rightarrow W$ .

(In example:  $\mathcal{P}_2 \cong \mathbb{R}^3$ ,  $ax^2+bx+c \mapsto \begin{pmatrix} a \\ b \\ c \end{pmatrix}$ )

Theorem 15.5 i) A lin. map  $F: V \rightarrow W$  is an isomorphism iff  $\text{Ker}(F) = \{0_V\}$  and  $\text{im}(F) = W$ .

ii) Let  $F: V \rightarrow W$  be an isomorphism and  $(b_1, \dots, b_n)$  a basis of  $V$ . Then  $(F(b_1), \dots, F(b_n))$  is a basis of  $W$ .

iii) Let  $V, W$  be fin. gen. and  $V \cong W$  then  $\dim(V) = \dim(W)$ .

iv) Let  $V, W$  be fin. gen. and  $\dim(V) = \dim(W)$ . Then for a lin. map  $F: V \rightarrow W$  the following statements are equivalent:

- (a)  $F$  is an isomorphism
- (b)  $\text{Ker}(F) = \{0_V\}$
- (c)  $\text{im}(F) = W$

Proposition 15.6 Let  $V$  be fin. gen. with basis  $B = (b_1, \dots, b_n)$ , i.e.  $\dim(V) = n$ . Then the coordinate map

$$C_B: \mathbb{R}^n \rightarrow V$$

$$\begin{pmatrix} \lambda_1 \\ \vdots \\ \lambda_n \end{pmatrix} \mapsto \sum_{i=1}^n \lambda_i b_i$$

is an isomorphism. The inverse is given by  $C_B^{-1}(x) = [u]_B$  for  $u \in V$ .

Example 53  $V = \mathcal{P}_2$ ,  $B = \left( \begin{matrix} x+1 & x^2-1 & x+3 \\ b_1 & b_2 & b_3 \end{matrix} \right)$

$C_B: \mathbb{R}^3 \rightarrow \mathcal{P}_2$  basis of  $V$ .

$$\begin{pmatrix} a \\ b \\ c \end{pmatrix} \mapsto a \overset{b_1}{(x+1)} + b \overset{b_2}{(x^2-1)} + c \overset{b_3}{(x+3)}$$

$$= (b)x^2 + (a+c)x + (a+3c)$$

$$C_B\left(\begin{pmatrix} 1 \\ -1 \\ 2 \end{pmatrix}\right) = -x^2 + 3x + 8$$

$\Rightarrow$  If  $f(x) = -x^2 + 3x + 8$  then  $[f]_B = \begin{pmatrix} 1 \\ -1 \\ 2 \end{pmatrix}$ .

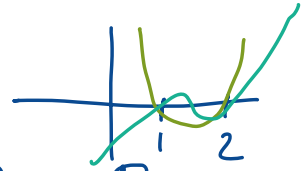
Corollary 15.7 Let  $V, W$  be fin. gen.. Then the

following two statements are equivalent

- i)  $V \cong W$
  - ii)  $\dim(V) = \dim(W)$ .
- (In particular:  $V \cong \mathbb{R}^n$  for some  $n \geq 1$ )

↑

### Example 54 (Similar to HW 1)



$$U = \{ f \in \mathcal{P}_3 \mid f(1) = f(2) = 0 \} \subset \mathcal{P}_3$$

A possible basis of  $U$  is  $B = (b_1, b_2)$

$$\begin{aligned} b_1(x) &= (x-1)(x-2), & b_2(x) &= (x-1)(x-2)(x+3) \\ &= x^2 - 3x + 2, & &= x^3 - 7x + 6 \end{aligned}$$

$\Rightarrow \dim U = 2 \Rightarrow U \cong \mathbb{R}^2$  *isomorphism is given by*  
 $C_B: \mathbb{R}^2 \rightarrow U$   
 $(\lambda_1, \lambda_2) \mapsto \lambda_1 b_1 + \lambda_2 b_2$

Let  $f(x) = (x-1)^2(x-2)$ . What is  $[f]_B$ ?

$$f(x) = \lambda_1 b_1(x) + \lambda_2 b_2(x) \quad \forall x \in \mathbb{R}$$

$$(x-1)^2(x-2) = \lambda_1 (x-1)(x-2) + \lambda_2 (x-1)(x-2)(x+3)$$

$$x-1 = \lambda_1 + \lambda_2(x+3)$$

$$0 = \underbrace{(\lambda_2 - 1)}_{=0} x + \underbrace{\lambda_1 + 1 + 3\lambda_2}_{=0}$$

$$\Rightarrow \lambda_2 = 1 \quad \lambda_1 = -4$$

$$[f]_B = \begin{pmatrix} -4 \\ 1 \end{pmatrix}$$

Here we use  $x$  and  $1$  are lin. indep.

## § 16 The matrix of a linear map

Goal: For fin. gen. vector spaces  $V, W$  and a linear map  $F: V \rightarrow W$  define "the" matrix of  $F$ .  $\mathbb{R}^n \xrightarrow{\quad} \mathbb{R}^m$

There are a lot of choices depending on bases of  $V$  and  $W$ .

Definition 16.1 Let  $V, W$  be fin. gen. vector spaces with bases  $B_V = (v_1, \dots, v_n)$  and  $B_W = (w_1, \dots, w_m)$ .

For a lin. map  $F: V \rightarrow W$  we define the matrix of  $F$  with respect to  $B_V$  and  $B_W$  by

$$[F]_{B_W}^{B_V} := [C_{B_W}^{-1} \circ F \circ C_{B_V}] . \quad \begin{array}{ccc} V & \xrightarrow{F} & W \\ C_{B_V} \uparrow & & \uparrow C_{B_W} \\ \mathbb{R}^n & \xrightarrow{G} & \mathbb{R}^m \end{array}$$

Here  $C_{B_W}^{-1} \circ F \circ C_{B_V}$  is the linear map  $\mathbb{R}^n \rightarrow \mathbb{R}^m$  for which we defined the matrix  $[G]$  in LA I. We have:

$$[G] = \begin{pmatrix} | & & | \\ G(e_1) & \dots & G(e_n) \\ | & & | \end{pmatrix}$$

And by  $G(e_j) = C_{B_w}^{-1} \left( F \left( \underbrace{C_{B_v}(e_j)}_{v_j} \right) \right)$  we get

$$\underbrace{\left[ F(v_j) \right]_{B_w}}_{[F(v_j)]_{B_w}}$$

$$[F]_{B_v}^{B_w} = \begin{pmatrix} | & & | \\ [F(v_1)]_{B_w} & \dots & [F(v_n)]_{B_w} \\ | & & | \end{pmatrix}$$

Special case:  $V=W$  and  $F = \text{identity (id}_V)$ :

Definition 16.2 Let  $B_1 = (v_1, \dots, v_n)$  and  $B_2 = (u_1, \dots, u_n)$  be bases of  $V$ . The change-of-basis matrix from  $B_1$  to  $B_2$  is the matrix

$$S_{B_1}^{B_2} = [\text{id}_V]_{B_1}^{B_2} = [C_{B_2}^{-1} C_{B_1}] = \begin{pmatrix} | & & | \\ [v_1]_{B_2} & \dots & [v_n]_{B_2} \\ | & & | \end{pmatrix}.$$

For  $v \in V$  we have

$$S_{B_1}^{B_2} [v]_{B_1} = [v]_{B_2}.$$

Example 55 Consider the linear map

$$D: P_2 \longrightarrow P_2$$

$$f \longmapsto f'$$

$$B = \begin{pmatrix} 1, & x, & x^2 \\ b_1 & b_2 & b_3 \end{pmatrix}, \quad C = \begin{pmatrix} 2, & 2x+4, & x^2 \\ c_1 & c_2 & c_3 \end{pmatrix}$$

We could calculate  $\underbrace{[D]_B^B}$ ,  $\underbrace{[D]_B^C}$ ,  $\underbrace{[D]_C^C}$ ,  $\underbrace{[D]_C^B}$

$$f(x) = ax^2 + bx + c \xrightarrow{D} f'(x) = 2ax + b$$

$$[f]_B = \begin{pmatrix} c \\ b \\ a \end{pmatrix} \xrightarrow{[D]_B^B} [D(f)]_B = \begin{pmatrix} b \\ 2a \\ 0 \end{pmatrix}$$

$$[f]_C = \begin{pmatrix} \frac{1}{2}c - b \\ \frac{1}{2}b \\ a \end{pmatrix} \xrightarrow{[D]_C^C} [D(f)]_C = \begin{pmatrix} \frac{1}{2}b - 2a \\ a \\ 0 \end{pmatrix}$$

$\downarrow S_B^C$  (orange arrow from  $[f]_B$  to  $[f]_C$ )  
 $[D]_B^C$  (green arrow from  $[f]_B$  to  $[D(f)]_C$ )  
 $[D]_C^B$  (purple arrow from  $[f]_C$  to  $[D(f)]_B$ )  
 $[D]_C^C$  (pink arrow from  $[f]_C$  to  $[D(f)]_C$ )

Calculate the matrices:

$$[D]_B^B = \begin{pmatrix} | & | & | \\ [D(b_1)]_B & [D(b_2)]_B & [D(b_3)]_B \\ | & | & | \end{pmatrix} = \boxed{\begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 2 \\ 0 & 0 & 0 \end{pmatrix}}$$

$$[D]_B^C = \begin{pmatrix} | & | & | \\ [D(b_1)]_C & [D(b_2)]_C & [D(b_3)]_C \\ | & | & | \end{pmatrix} = \begin{pmatrix} 0 & \frac{1}{2} & -2 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix}$$

$$B = \begin{pmatrix} 1 & x & x^2 \\ b_1 & b_2 & b_3 \end{pmatrix}, \quad C = \begin{pmatrix} 2 & 2x+4 & x^2 \\ c_1 & c_2 & c_3 \end{pmatrix}$$

$$D(b_1) = 0, \quad [D(b_1)]_B = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}, \quad [D(b_1)]_C = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$D(b_2) = 1, \quad [D(b_2)]_B = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \quad [D(b_2)]_C = \begin{pmatrix} \frac{1}{2} \\ 0 \\ 0 \end{pmatrix}$$

$$D(b_3) = 2x, \quad [D(b_3)]_B = \begin{pmatrix} 0 \\ 2 \\ 0 \end{pmatrix}, \quad [D(b_3)]_C = \begin{pmatrix} -2 \\ 1 \\ 0 \end{pmatrix}$$

$$S_B^C = \begin{pmatrix} | & | & | \\ [b_1]_C & [b_2]_C & [b_3]_C \\ | & | & | \end{pmatrix} = \begin{pmatrix} \frac{1}{2} & -1 & 0 \\ 0 & \frac{1}{2} & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$c_1 = \frac{1}{2}b_1, \quad c_2 = \frac{1}{2}b_2 - b_1, \quad c_3 = b_3$$

$$S_C^B = \begin{pmatrix} | & | & | \\ [c_1]_B & [c_2]_B & [c_3]_B \\ | & | & | \end{pmatrix} = \begin{pmatrix} 2 & 4 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$\frac{1}{2} \begin{pmatrix} 2 & 4 & 0 & | & 1 & 0 & 0 \\ 0 & 2 & 0 & | & 0 & 1 & 0 \\ 0 & 0 & 1 & | & 0 & 0 & 1 \end{pmatrix} \xrightarrow{\oplus} \begin{pmatrix} 1 & 2 & 0 & | & \frac{1}{2} & 0 & 0 \\ 0 & 1 & 0 & | & 0 & \frac{1}{2} & 0 \\ 0 & 0 & 1 & | & 0 & 0 & 1 \end{pmatrix} \sim \begin{pmatrix} 1 & 0 & 0 & | & \frac{1}{2} & -1 & 0 \\ 0 & 1 & 0 & | & 0 & \frac{1}{2} & 0 \\ 0 & 0 & 1 & | & 0 & 0 & 1 \end{pmatrix}$$

$$S_C^B = (S_B^C)^{-1}$$

Remarks: i) We have  $(S_{B_1}^{B_2})^{-1} = S_{B_2}^{B_1}$

ii) If we have base  $B_1, B_2, B_3, B_4$  of  $V$  and a linear map  $F: V \rightarrow V$ , then

$$[F]_{B_1}^{B_4} = S_{B_3}^{B_4} [F]_{B_2}^{B_3} S_{B_1}^{B_2}$$

Often:  $B_1 = B_4, B_2 = B_3$

Notation  $\rightarrow !!$

$$\begin{aligned}
 [F]_{B_1}^{B_1} &= S_{B_2}^{B_1} \overbrace{[F]_{B_2}^{B_2}}^{B_2} S_{B_1}^{B_2} \\
 &= (S_{B_1}^{B_2})^{-1} [F]_{B_2}^{B_2} S_{B_1}^{B_2} .
 \end{aligned}$$

iii)  $[F]_{B_1}^{B_1} = (S_{B_1}^{B_2})^{-1} [F]_{B_2}^{B_2} S_{B_1}^{B_2} (S_{B_1}^{B_2})^{-1} [F]_{B_2}^{B_2} S_{B_1}^{B_2}$

$$= (S_{B_1}^{B_2})^{-1} [F]_{B_2}^{B_2} S_{B_1}^{B_2}$$

Motivation: In applications we want to calculate

$[F]_{B_1}^n$ . For this we try to find  $B_2$

such that  $[F]_{B_2}^n$  is easy to  
calculate.

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e.g. diagonal matrix