

### Solution to the Review for the final exam

The following exercises are for the preparation of the final exam. The final exam will contain less exercises!

**Exercise 1.** We define the following matrix

$$A = \begin{pmatrix} 1 & 5 & 4 \\ 0 & 2 & 0 \\ 0 & 3 & 2 \end{pmatrix}.$$

i) Compute the determinant of  $A$ .

By Laplace Expansion over the 1<sup>st</sup> column we get

$$\begin{aligned} \det(A) &= (1) \det \begin{pmatrix} 2 & 0 \\ 3 & 2 \end{pmatrix} - (0) \det \begin{pmatrix} 5 & 4 \\ 4 & 2 \end{pmatrix} + (0) \det \begin{pmatrix} 5 & 4 \\ 3 & 2 \end{pmatrix} \\ &= (2 \cdot 2) - 0 - 0 + 0 = \underline{4}. \end{aligned}$$

ii) Find all eigenvalues of  $A$ . For each eigenvalue  $\lambda$  determine a basis of the eigenspace  $E_\lambda(A)$ .

We find the characteristic polynomial of  $A$  by considering the determinant of

$$A - \lambda I_3 = \begin{pmatrix} 1 - \lambda & 5 & 4 \\ 0 & 2 - \lambda & 0 \\ 0 & 3 & 2 - \lambda \end{pmatrix}$$

By Laplace Expansion over the 1<sup>st</sup> column we get

$$\begin{aligned} \det(A - \lambda I_3) &= (1 - \lambda) \det \begin{pmatrix} 2 - \lambda & 0 \\ 3 & 2 - \lambda \end{pmatrix} - (0) \det \begin{pmatrix} 5 & 4 \\ 3 & 2 - \lambda \end{pmatrix} + (0) \det \begin{pmatrix} 5 & 4 \\ 2 - \lambda & 0 \end{pmatrix} \\ &= (1 - \lambda)(2 - \lambda)(2 - \lambda) \end{aligned}$$

Which means that the eigenvalues of  $A$  are

$$\lambda = \underline{1} \quad \text{and} \quad \lambda = \underline{2}.$$

For  $\lambda = 1$ , let  $v \in \ker(A - I_3) = E_1(A)$ . Then  $v$  satisfies

$$\begin{pmatrix} 0 & 5 & 4 \\ 0 & 1 & 0 \\ 0 & 3 & 1 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \iff \begin{pmatrix} 5v_2 + 4v_3 \\ v_2 \\ 3v_2 + v_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

Solving the three linear equations give the result that

$$\ker(A - I_3) = E_1(A) = \text{span} \left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \right\} \iff B_1 = \underline{\underline{\left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \right\}}}$$
 is a basis of  $E_1(A)$ .

For  $\lambda = 2$ , let  $v \in \ker(A - 2I_3) = E_2(A)$ . Then  $v$  satisfies

$$\begin{pmatrix} -1 & 5 & 4 \\ 0 & 0 & 0 \\ 0 & 3 & 0 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \iff \begin{pmatrix} -v_1 + 5v_2 + 4v_3 \\ 0 \\ 3v_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

Solving the three linear equations give the result that

$$\ker(A - 2I_3) = E_2(A) = \text{span} \left\{ \begin{pmatrix} 4 \\ 0 \\ 1 \end{pmatrix} \right\} \iff B_2 = \underline{\underline{\left\{ \begin{pmatrix} 4 \\ 0 \\ 1 \end{pmatrix} \right\}}}$$
 is a basis of  $E_2(A)$ .

iii) Is  $A$  diagonalizable and/or invertible and/or orthogonal? Justify your answers.

$A$  is invertible since  $\det(A) = 4 \neq 0$ .

$A$  is not diagonalizable since we cannot find an eigenbasis of  $A$  (as  $\text{algmu}_A(2) = 2 > 1 = \text{geomu}_A(2)$ )

$A$  is not orthogonal since  $\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \bullet \begin{pmatrix} 4 \\ 0 \\ 2 \end{pmatrix} \neq 0$ .

**Exercise 2.** Decide if the following statements are true or false. Justify your answer by giving a short explanation (e.g. give a counterexample in the case when it is false).  $V$  is always a finitely generated vector space and  $A, B \in \mathbb{R}^{n \times n}$  are matrices.

1) The set  $U = \{p \in \mathcal{P}_2 \mid p(1) = p(2)\}$  is a subspace of  $\mathcal{P}_2$ .

True: Observe that the set  $U$  satisfies (three conditions of a subspace):

- i) Let the neutral element of  $\mathcal{P}_2$  be  $n(x) = 0$ . Then  $n(1) = n(2) = 0$ , so  $n \in U$ .
- ii) Let  $p$  and  $q$  be elements in  $U$ . Then we observe that

$$(p+q)(1) = p(1) + q(1) = p(2) + q(2) = (p+q)(2) \iff (p+q) \in U$$

iii) Let  $p \in U$  and  $\lambda \in \mathbb{R}$ . Then we observe that

$$(\lambda p)(1) = \lambda \cdot p(1) = \lambda \cdot p(2) = (\lambda p)(2) \iff (\lambda p) \in U$$

From which we conclude that  $U$  is a subspace of  $\mathcal{P}_2$ .

2) The set  $U = \{A \in \mathbb{R}^{2 \times 2} \mid A \text{ has eigenvalue } 1\}$  is a subspace of  $\mathbb{R}^{2 \times 2}$ .

False: Observe that  $I_2 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \in U$ , but  $2I_2 = \begin{pmatrix} 2 & 0 \\ 0 & 2 \end{pmatrix} \notin U$  as  $2I_2$  only has eigenvalue 2.

3) Every  $3 \times 3$  matrix has at least one eigenvalue.

True: The Characteristic Polynomial of a  $3 \times 3$  matrix is a  $3^{\text{rd}}$  degree polynomial. Every odd-degree polynomial always has at least one real zero (and therefore has at least one eigenvalue).

4) For any subspace  $U \subset V$ , there exist a linear map  $F : V \rightarrow V$  with  $\ker(F) = U$ .

True: As  $V$  is finitely generated, then  $U$  is also finitely generated. Let  $B_U = (u_1, \dots, u_m)$  be a basis of  $U$ . Then we can extend this to a basis of  $V$ ,  $B_V = (u_1, \dots, u_m, v_1, \dots, v_l)$ . Now we define the linear map  $F$  by  $F(u_j) = 0$  and  $F(v_i) = v_i$  for  $j \in [1, m]$  and  $i \in [1, l]$ . Then  $\ker(F) = U$ .

5) There exists a linear map  $F : \mathbb{R}^3 \rightarrow \mathbb{R}^3$  with  $\dim(\ker(F)) = \dim(\text{im}(F)) = 2$ .

False: By **Theorem 2.3**, we have that for a linear map  $F : V \rightarrow V$

$$\dim(V) = \dim(\ker(F)) + \dim(\text{im}(F))$$

And therefore here,  $\dim(\mathbb{R}^3) = 3 = \dim(\ker(F)) + \dim(\text{im}(F)) \neq 2 + 2$ , disproving the statement.

6) If  $(b_1, b_2)$  and  $(c_1, c_2)$  are two bases of a vector space  $V$ , then  $(b_1 + c_1, b_2 - c_2)$  is also a basis of  $V$ .

False: Let  $(b_1, b_2) = (c_1, c_2)$ . Then  $(b_1 + c_1, b_2 - c_2) = (2b_1, n_V)$  which is not a basis of  $V$  as  $n_V$  is linearly dependent with any other vector.

7) If  $\det(A) = 0$ , then  $A$  has at least one eigenvalue.

True:  $\det(A) = 0$  implies that  $\ker(A) \neq \{0\}$ . This means that  $\exists v \in \mathbb{R}^n$  such that  $Av = 0$ , implying that 0 is an eigenvalue of  $A$ .

8) If  $\det(A) > 0$ , then  $A$  has at least one eigenvalue.

False: Consider the matrix  $A = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$ .  $\det(A) = 1$ . The characteristic polynomial of  $A$  is  $\lambda^2 + 1$ . As such,  $A$  does not have any (real-valued) eigenvalue (as there exists no solutions to  $\lambda^2 + 1 = 0$ ).

9) If  $\det(A) = 0$  and  $\det(B) = 0$  then  $\det(A + B) = 0$ .

False: Let  $A = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$  and  $B = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$ . Then  $A + B = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = I_2$ . Here, observe that  $\det(A) = \det(B) = 0$  but  $\det(A + B) = \det(I_2) = 1 \neq 0$ .

10) There exist symmetric matrices without eigenvalues.

False: By the **Spectral Theorem**, all symmetric matrices are diagonalizable (and as such exists an eigenbasis of said symmetric matrices, implying the existence of at least one eigenvalue).

11) Every orthogonal matrix is invertible.

True: For an orthogonal matrix  $A$ , its inverse is given by  $A^T$ .

12) Let  $F : V \rightarrow V$  be a linear map. If  $F \circ F$  has at least one eigenvalue, then  $F$  also has at least one eigenvalue.

False: Consider the linear map

$$F : \mathbb{R}^2 \longrightarrow \mathbb{R}^2 \\ x \longmapsto \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} x$$

And then we have that  $F \circ F(x)$  is given by

$$F \circ F(x) = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} x = \begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix} x$$

Observe that  $F \circ F$  has eigenvalue  $-1$ .

However,  $F$  has no eigenvalues as the characteristic polynomial of  $F$  is equal to

$$p_F(\lambda) = \det \begin{pmatrix} -\lambda & -1 \\ 1 & -\lambda \end{pmatrix} = \lambda^2 + 1$$

And there exists no real-valued  $\lambda$  such that  $\lambda^2 + 1 = 0$ .

**Exercise 3.** Give an example of

i) a linear map  $F : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  with  $\dim(\ker(F)) = \dim(\text{im}(F)) = 1$ .

We consider the linear map

$$F : \mathbb{R}^2 \longrightarrow \mathbb{R}^2 \\ \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \longmapsto \begin{pmatrix} x_1 \\ 0 \end{pmatrix}$$

This implies that  $\ker(F) = \text{span} \left\{ \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right\}$  and  $\text{im}(F) = \text{span} \left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix} \right\}$ .

Therefore  $\dim \ker(F) = \dim \text{im}(F) = 1$ .

ii) a matrix  $A$  which is not symmetric but diagonalizable.

Consider the matrix  $A = \begin{pmatrix} 1 & 1 \\ 0 & 0 \end{pmatrix}$ . We have that the characteristic polynomial of  $A$  is

$$p_A(\lambda) = \det(A - \lambda I_2) = \det \begin{pmatrix} 1 - \lambda & 1 \\ 0 & -\lambda \end{pmatrix} = \lambda(\lambda - 1)$$

From which we conclude that the eigenvalues of  $A$  are  $\lambda = 0$  and  $\lambda = 1$

By **Corollary 5.7** we have that since  $A$  has 2 eigenvalues (and  $\dim \mathbb{R}^2 = 2$ ) then  $A$  is diagonalizable.

iii) a linear map  $F : \mathcal{P}_1 \rightarrow \mathcal{P}_1$  without eigenvalues.

Consider the linear map

$$\begin{aligned} F : \mathcal{P}_1 &\longrightarrow \mathcal{P}_1 \\ ax + b &\longmapsto -bx + a \end{aligned}$$

Consider  $B = (x, 1)$  which is one possible basis of  $\mathcal{P}_1$ .

Then we have that

$$[F]_B = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$$

And then we observe that the characteristic polynomial of  $F$  is  $P_F(\lambda) = \lambda^2 + 1$

From which we conclude that  $F$  has no eigenvalues.

iv) an orthogonal matrix  $A \in \mathbb{R}^{2 \times 2}$  without 0 as an entry.

$A = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ -1 & 1 \end{pmatrix}$  is orthogonal since

$$\frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ -1 \end{pmatrix} \cdot \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \frac{1}{2}((-1) + 1) = 0$$

and we have that

$$\left\| \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix} \right\| = \left\| \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ -1 \end{pmatrix} \right\| = 1.$$

**Exercise 4.** Let  $x_n \in \mathbb{R}^2$  be for  $n \geq 0$  be defined by

$$x_0 = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \quad \text{and} \quad x_{n+1} = Mx_n, \quad \text{where} \quad M = \begin{pmatrix} 1 & 1 \\ 3 & 3 \end{pmatrix}.$$

Determine an explicit formula for  $x_n$ .

We try to diagonalize  $M$ . First we find the characteristic polynomial of  $M$  which is given by:

$$p_M(\lambda) = \det \begin{pmatrix} 1-\lambda & 1 \\ 3 & 3-\lambda \end{pmatrix} = (\lambda-1)(\lambda-3) - 3 = \lambda^2 - 4\lambda = \lambda(\lambda-4)$$

From which we find that the eigenvalue of  $M$  are

$$\lambda_1 = 0 \quad \text{and} \quad \lambda_2 = 4.$$

Then we find the eigenvectors (and the eigenbasis) of  $M$ :

For  $\lambda = 0$ , let  $v \in E_0(M) = \ker(M)$ . Then  $v$  satisfies

$$\begin{aligned} \begin{pmatrix} 1 & 1 \\ 3 & 3 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} &= \begin{pmatrix} 0 \\ 0 \end{pmatrix} \\ \begin{pmatrix} v_1 + v_2 \\ 3v_1 + 3v_2 \end{pmatrix} &= \begin{pmatrix} 0 \\ 0 \end{pmatrix} \end{aligned}$$

From which we get the result that

$$\ker(M) = E_0(M) = \text{span} \left\{ \begin{pmatrix} 1 \\ -1 \end{pmatrix} \right\}$$

For  $\lambda = 4$ , let  $v \in E_4(M) = \ker(M - 4I_2)$ . Then  $v$  satisfies

$$\begin{pmatrix} -3 & 1 \\ 3 & -1 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} -3v_1 + v_2 \\ 3v_1 - v_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

From which we get the result that

$$\ker(M) = E_0(M) = \text{span} \left\{ \begin{pmatrix} 1 \\ 3 \end{pmatrix} \right\}$$

We then conclude that  $B = \left( \begin{pmatrix} 1 \\ -1 \end{pmatrix}, \begin{pmatrix} 1 \\ 3 \end{pmatrix} \right)$  is an eigenbasis of  $M$ .

Thus if we set  $S := \begin{pmatrix} 1 & 1 \\ -1 & 3 \end{pmatrix}$  we have that

$$S^{-1}MS = \begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 0 & 4 \end{pmatrix}$$

We can find the inverse of  $S$ ,  $S^{-1}$  by:

$$S^{-1} = \frac{1}{\det(S)} \begin{pmatrix} 3 & -1 \\ 1 & 1 \end{pmatrix} = \frac{1}{3+1} \begin{pmatrix} 3 & -1 \\ 1 & 1 \end{pmatrix} = \frac{1}{4} \begin{pmatrix} 3 & -1 \\ 1 & 1 \end{pmatrix}$$

We observe that

$$M = S \begin{pmatrix} 0 & 0 \\ 0 & 4 \end{pmatrix} S^{-1} \iff M^n = S \begin{pmatrix} 0 & 0 \\ 0 & 4 \end{pmatrix}^n S^{-1}$$

As  $S^{-1}S = SS^{-1} = I_2$ . We observe that  $M^n x_0 = x_n$ , so we get that

$$\begin{aligned} x_n &= S \begin{pmatrix} 0 & 0 \\ 0 & 4 \end{pmatrix}^n S^{-1} x_0 \\ &= \begin{pmatrix} 1 & 1 \\ -1 & 3 \end{pmatrix} \begin{pmatrix} 0 & 0 \\ 0 & 4^n \end{pmatrix} \frac{1}{4} \begin{pmatrix} 3 & -1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} \\ &= \frac{1}{4} \begin{pmatrix} 0 & 4^n \\ 0 & 3 \cdot 4^n \end{pmatrix} \begin{pmatrix} 3 & -1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} \\ &= \frac{1}{4} \begin{pmatrix} 4^n & -4^n \\ 3 \cdot 4^n & -3 \cdot 4^n \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} \\ &= \frac{1}{4} \begin{pmatrix} 4^n \\ 3 \cdot 4^n \end{pmatrix} = \underline{\underline{\begin{pmatrix} 4^{n-1} \\ 3 \cdot 4^{n-1} \end{pmatrix}}}. \end{aligned}$$

**Remark:** This formula is valid for  $n \geq 1$ , and isn't valid for  $n = 0$ , as  $x_0$  is defined arbitrarily.

**Exercise 5.** Let  $F : \mathcal{P}_2 \rightarrow \mathcal{P}_2$  be the linear map given by

$$F(p)(t) = tp'(t) + 2p(t).$$

Calculate the determinant of  $F$ .

If we want to find  $\det(F)$  we can define a basis  $B$  of  $\mathcal{P}_2$  and then we have that  $\det[F]_B = \det(F)$ .

Let  $B = (b_1, b_2, b_3) = (t^2, t, 1)$ . Then to find  $[F]_B$  we find:

$$F(b_1) = t(2t) + 2(t^2) = 4t^2 = 4b_1$$

$$F(b_2) = t(1) + 2(t) = 3t = 3b_2$$

$$F(b_3) = t(0) + 2(1) = 2 = 2b_3$$

From which we have the result that

$$[F]_B = \begin{pmatrix} \left| \begin{array}{c} [F(b_1)]_B \\ \hline \end{array} \right| & \left| \begin{array}{c} [F(b_2)]_B \\ \hline \end{array} \right| & \left| \begin{array}{c} [F(b_3)]_B \\ \hline \end{array} \right| \end{pmatrix} = \begin{pmatrix} 4 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 2 \end{pmatrix} \implies \det(F) = \det[F]_B = \underline{24}.$$

**Exercise 6.** Let  $V$  be a finitely generated vector space and  $P : V \rightarrow V$  be a linear map with  $P \circ P = P$ . Assume that  $\lambda$  is an eigenvalue of  $P$ . What are the possible values of  $\lambda$ ?

Let  $v \in V$  ( $v \neq n_V$ ) be an eigenvector of  $P$  with eigenvalue  $\lambda$ . Then,

$$P(v) = \lambda \cdot v$$

And the equality  $P \circ P = P$  implies that

$$\begin{aligned} P \circ P(v) &= P(v) \\ \iff P(\lambda \cdot v) &= \lambda \cdot v \\ \iff \lambda \cdot \lambda \cdot v &= \lambda v \\ \iff (\lambda^2 - \lambda)v &= n_V \\ \iff \lambda(\lambda - 1)v &= n_V \end{aligned}$$

Since  $v \neq n_V$  we get that  $\lambda(\lambda - 1) = 0$ . As such, the only possible values of  $\lambda$  are:

$$\lambda = \underline{0} \quad \text{and} \quad \lambda = \underline{1}.$$

**Exercise 7.** Find all solutions to the following differential equation

$$f''' - 2f'' = 4,$$

such that  $f(0) = f'(0) = f''(0) = 0$ .

We have the differential operator

$$T(f) = f''' - 2f''$$

And want to find the solutions to  $T(f) = 4$ .

First we find one particular solution.  $f_p(t) = -t^2$  is a solution as

$$f_p'''(t) - 2f_p''(t) = 0 - 2(-2) = 4$$

Now we determine the kernel of  $T$  by finding the characteristic polynomial of  $T$ :

$$\begin{aligned} P_T(x) &= x^3 - 2x^2 \\ &= x^2(x - 2) \end{aligned}$$

Therefore the zeroes of the characteristic polynomial are 0 and 2.

Then we know that the kernel of  $T$  is given by

$$\ker(T) = \text{span}\{e^{0t}, te^{0t}, e^{2t}\} = \text{span}\{1, t, e^{2t}\}$$

Which means that all solutions to  $T(f) = 4$  are given by

$$f(t) = -t^2 + c_1 + c_2t + c_3e^{2t} \quad \text{for } c_1, c_2, c_3 \in \mathbb{R}.$$

Now we want to find the solutions that satisfy  $f(0) = 0$ ,  $f'(0) = 0$  and  $f''(0) = 0$ :

$$\begin{aligned}f(0) = 0 &\iff 0 = -(0)^2 + c_1 + c_2(0) + c_3(1) = c_1 + c_3 \\f'(0) = 0 &\iff 0 = (-2)(0) + 0 + c_2 + c_3(2)(1) = c_2 + 2c_3 \\f''(0) = 0 &\iff 0 = -2 + 0 + 4c_3(1) = -2 + 4c_3\end{aligned}$$

This corresponds to the matrix equation

$$\begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 2 \\ 0 & 0 & 4 \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \\ c_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 2 \end{pmatrix}$$

Solving these three linear equations gives us the result that

$$c_3 = \frac{1}{2} \quad c_2 = -2c_3 = -1 \quad c_1 = -c_3 = -\frac{1}{2}.$$

Which means that

$$f(t) = \underline{\underline{\frac{1}{2}e^{2t} - t^2 - t - \frac{1}{2}}}$$

is a solution to  $T(f) = 4$  and satisfies  $f(0) = f'(0) = f''(0) = 0$ .

終わり