Instructor: Henrik Bachmann Teaching assistant: Yuichiro Toma

**Tutorial 9: Inverses and subspaces** 

Exercise 1. Decide if the following two linear maps are invertible. Determine their inverses if they exist.

$F: \mathbb{R}^3 \longrightarrow \mathbb{R}^3$ ,	$G: \mathbb{R}^3 \longrightarrow \mathbb{R}^3$ ,
$ \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} \longmapsto \begin{pmatrix} 2x_2 + 2x_3 \\ x_1 - 4x_2 + 6x_3 \\ x_2 + x_3 \end{pmatrix} , $	$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} \longmapsto \begin{pmatrix} 10x_1 + x_2 - 26x_3 \\ x_1 - 2x_3 \\ -x_1 + x_3 \end{pmatrix} \cdot \begin{pmatrix} \mathbf{q} \\ \mathbf{z} - 2 - \mathbf{q} \\ \mathbf{z} \end{pmatrix}$
<b>Exercise 2.</b> (Final Exam 2021) Let $A = \begin{pmatrix} 1 & 2 & 3 \\ 0 & 1 & -2 \\ 1 & 2 & 5 \end{pmatrix}$	and $B = \begin{pmatrix} 1 & 2 & 3 \\ 4 & 1 & -2 \\ -1 & 2 & 5 \end{pmatrix}$ . B not invertible
<ul> <li>(i) Determine whether or not the matrices A and B are invertible and, if they are, compute their inverses.</li> <li>(ii) Calculate the matrix BA and decide if BA<sup>n</sup> is invertible for any integer n ≥ 1</li> </ul>	
	If $BA^n$ inv. then $B = BA^n \cdot (A^n)^{t}$ would
(Next lecture) A subset $U \subset \mathbb{R}^n$ is a <b>subspace</b> of $\mathbb{R}^n$ if	be (nr.
i) $0 \in U$ ,	$\Rightarrow BA$
ii) for all $u, v \in U$ we have $u + v \in U$ ,	not inv.
iii) for all $u \in U$ and $\lambda \in \mathbb{R}$ we have $\lambda u \in U$ .	

(Next lecture) The **span** of  $v_1, \ldots, v_n \in \mathbb{R}^m$  is the set  $\operatorname{span}\{v_1, \ldots, v_n\} = \{\lambda_1 v_1 + \cdots + \lambda_n v_n \in \mathbb{R}^m \mid \lambda_1, \ldots, \lambda_n \in \mathbb{R}\}.$ 

**Exercise 3.** (Final Exam 2019) Which of the following subsets of  $\mathbb{R}^2$  are subspaces? Justify your answers.

(i) 
$$U_1 = \left\{ \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \in \mathbb{R}^2 \mid x_1 + x_2 = x_1 x_2 \right\}$$
. Vc  
(ii)  $U_2 = \left\{ \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \in \mathbb{R}^2 \mid 2x_1 = x_1 + x_2 \right\}$ . Ves

(iii) 
$$U_3 = \operatorname{span}\left\{ \begin{pmatrix} 2\\2 \end{pmatrix} \right\} \bigcup \operatorname{span}\left\{ \begin{pmatrix} 2\\1 \end{pmatrix} \right\}.$$
 No

(Reminder:  $\cup$  is the union of two sets)

(Solutions for Exercise 2 & 3 are contained in the solutions for the Final exam 2021 & 2019)

Version: November 28, 2023

## Homework 4: Reflection, Projection and Inverses

Deadline: 3rd December, 2023

**Exercise 1.** (2+3 = 5 Points) Let 
$$u = \begin{pmatrix} u_1 \\ \vdots \\ u_n \end{pmatrix} \in \mathbb{R}^n$$
 be with  $u \neq 0$ .

- (i) Show that the reflection  $\rho_u : \mathbb{R}^n \longrightarrow \mathbb{R}^n$  is a linear map.
- (ii) Show that the matrix of the projection  $P_u : \mathbb{R}^n \longrightarrow \mathbb{R}^n$  is given by

$$[P_u] = \frac{1}{u \bullet u} u u^T \in \mathbb{R}^{n \times n} ,$$

where  $u^T = (u_1 \, u_2 \, \dots \, u_n) \in \mathbb{R}^{1 \times n}$ . Use this to give an expression for  $[\rho_u]$ .

**Exercise 2.** 
$$(2+3 = 5 \text{ Points})$$
 Let  $u = \begin{pmatrix} 2 \\ 1 \end{pmatrix}, d = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$  and  $x = \begin{pmatrix} 5 \\ 0 \end{pmatrix}$ .

- (i) Calculate the matrices  $[P_u]$  and  $[\rho_u]$  in this special case.
- (ii) Calculate the following vectors and draw them in one picture together with u,d and x

$$P_u(x), \quad \rho_u(x), \quad (P_u \circ P_d)(x), \quad \operatorname{rot}_{\frac{\pi}{2}}(x), \quad (P_u \circ \operatorname{rot}_{\frac{\pi}{2}})(x), \quad (\operatorname{rot}_{\frac{\pi}{2}} \circ P_u)(x),$$

**Exercise 3.** (2+2 = 4 Points) Show that for all  $u \in \mathbb{R}^n$  with  $u \neq 0$  the projection  $P_u$  and the reflection  $\rho_u$  satisfy for all  $x \in \mathbb{R}^n$  the following two properties:

- (i)  $P_u(P_u(x)) = P_u(x)$ .
- (ii)  $\rho_u(\rho_u(x)) = x$ .

**Exercise 4.** (3+3=6 Points)

(i) Decide if the following two linear maps are invertible. Determine their inverses if they exist.

$$F: \mathbb{R}^{3} \longrightarrow \mathbb{R}^{3}, \qquad G: \mathbb{R}^{3} \longrightarrow \mathbb{R}^{3}, \\ \begin{pmatrix} x_{1} \\ x_{2} \\ x_{3} \end{pmatrix} \longmapsto \begin{pmatrix} -x_{1} + x_{2} + 5x_{3} \\ 2x_{1} - x_{2} + 2x_{3} \\ -x_{1} + x_{2} + 4x_{3} \end{pmatrix}, \qquad \begin{pmatrix} x_{1} \\ x_{2} \\ x_{3} \end{pmatrix} \longmapsto \begin{pmatrix} x_{1} + x_{2} + 2x_{3} \\ 2x_{1} + 2x_{2} + 4x_{3} \\ 2x_{1} + 3x_{2} + 5x_{3} \end{pmatrix}.$$

(ii) The **kernel** of a linear map  $H : \mathbb{R}^n \to \mathbb{R}^m$  is defined by

$$\ker(H) = \left\{ x \in \mathbb{R}^n \mid H(x) = 0 \right\}.$$

Determine  $\ker(F)$  and  $\ker(G)$ .

Exercise 1. Decide if the following two linear maps are invertible. Determine their inverses if they exist.

$$F: \mathbb{R}^3 \longrightarrow \mathbb{R}^3, \qquad G: \mathbb{R}^3 \longrightarrow \mathbb{R}^3, \\ \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} \longmapsto \begin{pmatrix} 2x_2 + 2x_3 \\ x_1 - 4x_2 + 6x_3 \\ x_2 + x_3 \end{pmatrix}, \qquad \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} \longmapsto \begin{pmatrix} 10x_1 + x_2 - 26x_3 \\ x_1 - 2x_3 \\ -x_1 + x_3 \end{pmatrix}.$$

The matrix of 
$$\mp$$
 is  $[F] = \begin{pmatrix} 0 & 2 & 2 \\ 1 & -4 & 6 \\ 0 & 1 & 1 \end{pmatrix}$ . We calculate:  
 $\left( [F] | I_3 \right) = \begin{bmatrix} 2 & 0 & 2 & 2 & | & 1 & 0 & 0 \\ 1 & -4 & 6 & | & 0 & 1 & 0 \\ 0 & 1 & 1 & | & 0 & 0 & 1 \end{pmatrix} \sim \begin{bmatrix} 1 & -4 & 6 & | & 0 & 1 & 0 \\ 0 & 2 & 2 & | & 1 & 0 & 0 \\ 0 & 1 & 1 & | & 0 & 0 & 1 & 0 \\ 0 & 1 & 1 & | & 0 & 0 & 1 & 0 \end{bmatrix}$   
 $\sim \begin{pmatrix} 1 & -4 & 6 & | & 0 & 1 & 0 \\ 0 & 2 & 2 & | & 1 & 0 & 0 \\ 0 & 0 & 0 & | & -\frac{1}{2} & 0 & 1 \end{pmatrix}$ 

Here we already see that  $rref([F]) \neq I_3$  and therefore F is not invertible.

For G we have 
$$[G] = \begin{pmatrix} 10 & 1 & -26 \\ 1 & 0 & -2 \\ -1 & 0 & 1 \end{pmatrix}$$
 and we get  
 $([G] | I_3) \stackrel{f}{=} \stackrel{(10 & 1 - 26 \\ 1 & 0 & -2 \\ -1 & 0 & 1 \end{pmatrix} \stackrel{(100)}{=} \stackrel{(100)}$ 

Therefore G is invertible and the inverse is given by  $G^{-1}: [R^{3} \longrightarrow R^{3}]$  $X = \begin{pmatrix} x_{1} \\ x_{2} \\ x_{3} \end{pmatrix} \mapsto \begin{pmatrix} -x_{2} - 2x_{3} \\ x_{1} - 16x_{2} - 6x_{3} \\ -x_{2} - x_{3} \end{pmatrix} = [G^{-1}x].$ 

Additional question: What is Ker(F), Ker(G)?  $|(e_r(F) = \{x \in R^3 | F(x) = 0\}$ By above calculation:  $\sim \begin{pmatrix} | & O & | 0 \\ 0 & | & | \\ 0 & ( ) & 0 \end{pmatrix}$  $\chi_{l} = -lot$  $X_1 = -t$ Solutions to F(x)=0:  $X_{7} = t$ 

 $V(r(F) = \{ X \in \mathbb{R}^3 \mid X = t \begin{pmatrix} -lo \\ -l \end{pmatrix}, t \in \mathbb{R}^3 \}$ 

Since G is invertible, G(x)=0 just has the solution X=0, i.e. Kev(G) = FOG.