

Tutorial 3&4

24

Tutorial 3: Matrices & Vectors

Recall that a $m \times n$ -**matrix** is given by an array (with m rows and n columns) of numbers $a_{ij} \in \mathbb{R}$

$$A = \begin{pmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{pmatrix} = (a_{ij})_{\substack{1 \leq i \leq m \\ 1 \leq j \leq n}} = (a_{ij})_{ij}.$$

By $\mathbb{R}^{m \times n} = M_{m \times n}(\mathbb{R})$ we denote the set of all $m \times n$ -matrices.

A (column-) **vector** of size n is a $n \times 1$ -matrix

$$v = \begin{pmatrix} v_1 \\ \vdots \\ v_n \end{pmatrix}$$

and the set of all vectors of size n is denoted by $\mathbb{R}^n = \mathbb{R}^{n \times 1}$. For $A, B \in \mathbb{R}^{m \times n}$ and $\lambda \in \mathbb{R}$ we defined

$$A + B = (a_{ij} + b_{ij})_{ij} \in \mathbb{R}^{m \times n} \quad (\text{Sum of two matrices}),$$

$$\lambda A = (\lambda a_{ij})_{ij} \in \mathbb{R}^{m \times n} \quad (\text{Scalar multiplication}).$$

In the case $\lambda = -1$ we write $(-1)A = -A$ and $A - B$ means $A + (-1)B$.

The product of a matrix $A \in \mathbb{R}^{m \times n}$ and a vector $v \in \mathbb{R}^n$ is defined by

$$Av = \begin{pmatrix} a_{11} & \cdots & a_{1n} \\ \vdots & \ddots & \vdots \\ a_{m1} & \cdots & a_{mn} \end{pmatrix} \begin{pmatrix} v_1 \\ \vdots \\ v_n \end{pmatrix} = \begin{pmatrix} a_{11}v_1 + a_{12}v_2 + \cdots + a_{1n}v_n \\ a_{21}v_1 + a_{22}v_2 + \cdots + a_{2n}v_n \\ \vdots \\ a_{m1}v_1 + a_{m2}v_2 + \cdots + a_{mn}v_n \end{pmatrix} \in \mathbb{R}^m \quad (\text{Matrix-vector multiplication}).$$

In other words we have: $(m \times n\text{-matrix}) \cdot (\text{vector of size } n) = (\text{vector of size } m)$.

Example: $m = 2, n = 3$

$$\begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{pmatrix} \begin{pmatrix} 7 \\ 8 \\ 9 \end{pmatrix} = \begin{pmatrix} 1 \cdot 7 + 2 \cdot 8 + 3 \cdot 9 \\ 4 \cdot 7 + 5 \cdot 8 + 6 \cdot 9 \end{pmatrix} = \begin{pmatrix} 50 \\ 122 \end{pmatrix}.$$

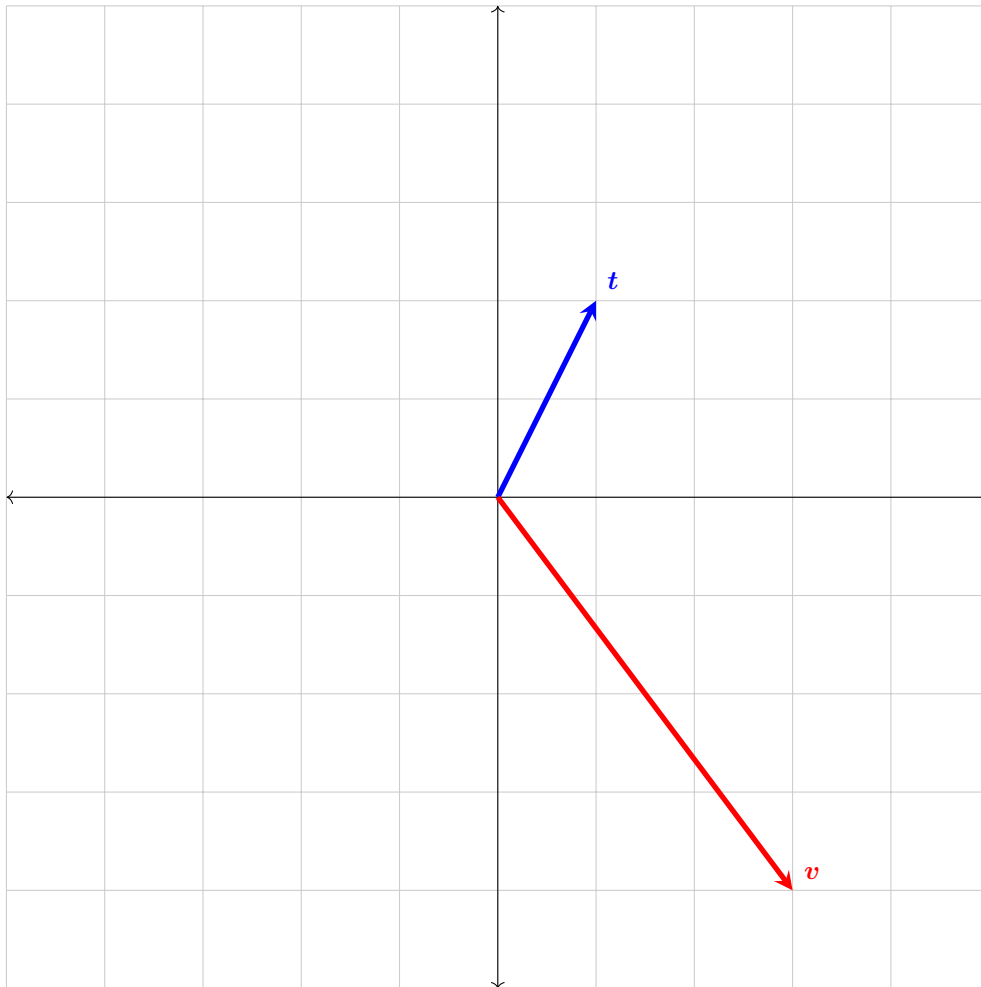
Exercise 1. We define the following matrices and vectors:

$$A = \begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{pmatrix}, \quad B = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}, \quad C = \begin{pmatrix} -1 & 0 \\ 2 & 4 \\ 0 & -3 \end{pmatrix}, \quad D = \begin{pmatrix} 0 & 8 & 0 \\ 1 & 2 & -1 \end{pmatrix}, \quad E = \begin{pmatrix} 3 & -4 \\ 5 & 5 \\ 4 & 3 \\ 5 & 5 \end{pmatrix},$$
$$t = \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \quad u = \begin{pmatrix} 1 \\ -1 \\ 2 \end{pmatrix}, \quad v = \begin{pmatrix} 3 \\ -4 \end{pmatrix}, \quad w = \begin{pmatrix} -1 \\ 2 \\ 2 \end{pmatrix}.$$

Decide which of the following expressions are defined. Evaluate them if possible.

$$At, \quad Au, \quad wA, \quad 2A, \quad A+B, \quad A+C, \quad A+D, \quad \frac{3}{4}Bt, \quad Bu, \quad B+B, \quad Dw, \\ Cv, \quad t+u, \quad tu, \quad -v, \quad u+w, \quad t-u, \quad \frac{1}{2}w, \quad C+w, \quad Et, \quad Ev, \quad E(Ev).$$

Exercise 2. The vectors t and v of Exercise 1 are drawn in the following diagram.



Draw the following vectors in the diagram:

$$-2t, \quad t - \frac{1}{2}v, \quad v+t, \quad t+v, \quad Et, \quad Ev, \quad E(Ev), \quad Bt, \quad Bv.$$

Can you guess what happens in general to a vector in \mathbb{R}^2 when you multiply it with B or E ?

Exercise 3.

- i) Calculate the rank of the matrices in Exercise 1.
- ii) Find a vector $x \in \mathbb{R}^2$, such that $Ex = t$ and draw it in the diagram above.
- iii) Find a matrix $M \in \mathbb{R}^{2 \times 2}$ with $Mv = t$. Is this matrix unique?

Homework 2: Matrices & Vectors

Deadline: 29th October, 23:55, 2023

Exercise 1. (2+2 = 4 Points) Show that for all $A \in \mathbb{R}^{m \times n}$, $x, y \in \mathbb{R}^n$ and $\lambda \in \mathbb{R}$ we have

(i) $A(x + y) = Ax + Ay$,

(ii) $A(\lambda x) = \lambda(Ax)$.

(Without using Proposition 2.4. from the lecture).

Let $A \in \mathbb{R}^{m \times n}$ be a matrix. The **rank** $\text{rk}(A)$ of A is the number of pivot elements in $\text{rref}(A)$.
For example,

$$A = \begin{pmatrix} 1 & 1 & 0 \\ 2 & 0 & 1 \\ 1 & -1 & 1 \end{pmatrix} \sim \begin{pmatrix} 1 & 1 & 0 \\ 0 & -2 & 1 \\ 0 & -2 & 1 \end{pmatrix} \sim \begin{pmatrix} 1 & 1 & 0 \\ 0 & -2 & 1 \\ 0 & 0 & 0 \end{pmatrix} \sim \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & -\frac{1}{2} \\ 0 & 0 & 0 \end{pmatrix} \sim \begin{pmatrix} 1 & 0 & \frac{1}{2} \\ 0 & 1 & -\frac{1}{2} \\ 0 & 0 & 0 \end{pmatrix} = \text{rref}(A)$$

and therefore the rank of A is $\text{rk}(A) = 2$.

Exercise 2. (2+1+3 = 6 Points) Let $p(x) = a_0 + a_1x + a_2x^2 + a_3x^3$ be a polynomial of degree 3 with real coefficients $a_0, a_1, a_2, a_3 \in \mathbb{R}$. For such a polynomial p define the vector v_p by

$$v_p = \begin{pmatrix} a_0 \\ a_1 \\ a_2 \\ a_3 \end{pmatrix} \in \mathbb{R}^4.$$

(i) Find a matrix $D \in \mathbb{R}^{4 \times 4}$, such that $v_q = Dv_p$, where $q(x) = 2p(x) - p'(x)$.

(Here p' denotes the derivative of the polynomial p with respect to x).

(ii) Determine the rank of D in (i).

(iii) For an arbitrary polynomial p of degree 3, find a polynomial s , such that $v_p = Dv_s$.

Exercise 3. (2+2 = 4 Points) Let $A \in \mathbb{R}^{3 \times 3}$ be a matrix.

(i) Show that if $\text{rk}(A) = 3$ then there exists just one vector $x \in \mathbb{R}^3$ with $Ax = 0$.

(ii) Show that if $\text{rk}(A) \leq 2$ then there exist infinitely many vectors $x \in \mathbb{R}^3$ with $Ax = 0$.

Exercise 4. (4+2 = 6 Points) Let $a, b, c, d \in \mathbb{R}$ and $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$.

(i) Show that $\text{rk}(A) = 2$ if and only if $ad - bc \neq 0$.

(ii) We define the following subset of \mathbb{R}^2

$$L = \{x \in \mathbb{R}^2 \mid x = Av \text{ for some } v \in \mathbb{R}^2\}.$$

How does L look like if $\text{rk}(A) = 1$? How does it look like if $\text{rk}(A) = 2$?

Solution to the Tutorial Exercises:

$$A = \begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{pmatrix}, \quad B = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}, \quad C = \begin{pmatrix} -1 & 0 \\ 2 & 4 \\ 0 & -3 \end{pmatrix}, \quad D = \begin{pmatrix} 0 & 8 & 0 \\ 1 & 2 & -1 \end{pmatrix}, \quad E = \begin{pmatrix} 3 & -4 \\ 5 & 5 \\ 4 & 3 \\ 5 & 5 \end{pmatrix},$$

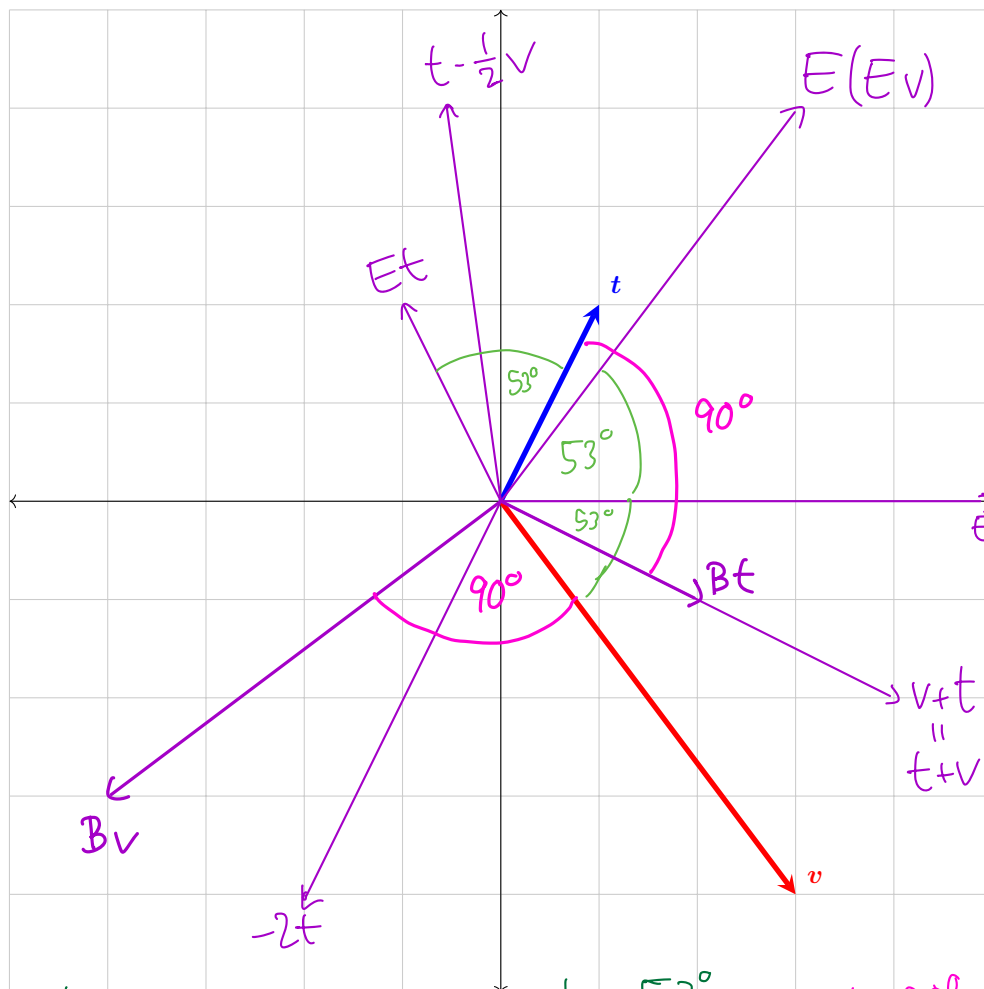
$$t = \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \quad u = \begin{pmatrix} 1 \\ -1 \end{pmatrix}, \quad v = \begin{pmatrix} 3 \\ -4 \end{pmatrix}, \quad w = \begin{pmatrix} -1 \\ 2 \end{pmatrix}.$$

Decide which of the following expressions are defined. Evaluate them if possible.

~~A~~ , Au , ~~wA~~ , $2A$, ~~$A \times B$~~ , ~~$A \times C$~~ , $A + D$, $\frac{3}{4}Bt$, ~~Eu~~ , $B + B$, Dw ,
 Cv , ~~$t \times u$~~ , ~~tu~~ , $-v$, $u + w$, ~~$t \times v$~~ , $\frac{1}{2}w$, ~~$C \times w$~~ , Et , Ev , $E(Ev)$.

$X =$ Not defined
 (Either wrong dimension or just not defined)

Exercise 2. The vectors t and v of Exercise 1 are drawn in the following diagram.



$$Au = \begin{pmatrix} 5 \\ 11 \end{pmatrix}$$

$$2A = \begin{pmatrix} 2 & 4 & 6 \\ 8 & 10 & 12 \end{pmatrix}$$

$$A + D = \begin{pmatrix} 1 & 10 & 3 \\ 5 & 7 & 5 \end{pmatrix}$$

$$\frac{3}{4}Bt = \begin{pmatrix} \frac{3}{2} \\ -\frac{3}{4} \end{pmatrix}$$

$$B + B = \begin{pmatrix} 0 & 2 \\ -2 & 0 \end{pmatrix}$$

$$Dw = \begin{pmatrix} 16 \\ 1 \end{pmatrix}$$

$$Cv = \begin{pmatrix} -3 \\ 10 \\ 12 \end{pmatrix}$$

$$-v = \begin{pmatrix} -3 \\ 4 \end{pmatrix}$$

$$u + w = \begin{pmatrix} 0 \\ 4 \end{pmatrix}$$

$$\frac{1}{2}w = \begin{pmatrix} -\frac{1}{2} \\ 1 \end{pmatrix}$$

$$Et = \begin{pmatrix} -1 \\ 2 \end{pmatrix}$$

$$Ev = \begin{pmatrix} 5 \\ 0 \end{pmatrix}$$

$$E(Ev) = \begin{pmatrix} 3 \\ 4 \end{pmatrix}$$

$$-2t = \begin{pmatrix} -2 \\ -4 \end{pmatrix}$$

$$t - \frac{1}{2}v = \begin{pmatrix} 1 \\ 2 \end{pmatrix} - \begin{pmatrix} \frac{3}{2} \\ -2 \end{pmatrix} = \begin{pmatrix} -\frac{1}{2} \\ 4 \end{pmatrix}$$

Multiplying with E : Rotation by 53°
 Mult. by B : Rotation by 90°

Draw the following vectors in the diagram:

$$-2t, \quad t - \frac{1}{2}v, \quad v + t, \quad t + v, \quad Et, \quad Ev, \quad E(Ev), \quad Bt, \quad Bv.$$

Can you guess what happens in general to a vector in \mathbb{R}^2 when you multiply it with B or E ?

Exercise 3.

- Calculate the rank of the matrices in Exercise 1.
- Find a vector $x \in \mathbb{R}^2$, such that $Ex = t$ and draw it in the diagram above.
- Find a matrix $M \in \mathbb{R}^{2 \times 2}$ with $Mv = t$. Is this matrix unique?

$$Bt = \begin{pmatrix} 2 \\ -1 \end{pmatrix}$$

$$Bv = \begin{pmatrix} -4 \\ -3 \end{pmatrix}$$

3) i)

$$A = \begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{pmatrix}, \quad B = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}, \quad C = \begin{pmatrix} -1 & 0 \\ 2 & 4 \\ 0 & -3 \end{pmatrix}, \quad D = \begin{pmatrix} 0 & 8 & 0 \\ 1 & 2 & -1 \end{pmatrix}, \quad E = \begin{pmatrix} 3 & -4 \\ 4 & 3 \\ 4 & 3 \end{pmatrix},$$

$$A \sim \begin{pmatrix} 1 & 2 & 3 \\ 0 & -3 & -6 \end{pmatrix} \sim \begin{pmatrix} 1 & 2 & 3 \\ 0 & 1 & 2 \end{pmatrix} \sim \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 2 \end{pmatrix} = \text{rref}(A)$$

$$\Rightarrow \text{rk}(A) = 2$$

$$\text{rk}(B) = 2, \quad \text{rk}(C) = 2, \quad \text{rk}(D) = 2$$

$$\text{rk}(E) = 2$$

ii) Find $x \in \mathbb{R}^2$ with $Ex = t \Leftrightarrow \begin{pmatrix} \frac{3}{5} & -\frac{4}{5} \\ \frac{4}{5} & \frac{3}{5} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$

$$(E|t) = \begin{pmatrix} \frac{3}{5} & -\frac{4}{5} & | & 1 \\ \frac{4}{5} & \frac{3}{5} & | & 2 \end{pmatrix} \sim \begin{pmatrix} 3 & -4 & | & 5 \\ 4 & 3 & | & 10 \end{pmatrix}$$

$$\sim \begin{pmatrix} 3 & -4 & | & 5 \\ 1 & 7 & | & 5 \end{pmatrix} \sim \begin{pmatrix} 0 & -25 & | & -10 \\ 1 & 7 & | & 5 \end{pmatrix}$$

$$\sim \begin{pmatrix} 1 & 7 & | & 5 \\ 0 & -25 & | & -10 \end{pmatrix} \sim \begin{pmatrix} 1 & 7 & | & 5 \\ 0 & 1 & | & \frac{2}{5} \end{pmatrix}$$

$$\sim \begin{pmatrix} 1 & 0 & | & \frac{11}{5} \\ 0 & 1 & | & \frac{2}{5} \end{pmatrix} \quad \text{Solution: } x = \begin{pmatrix} \frac{11}{5} \\ \frac{2}{5} \end{pmatrix}$$

iii) Find $M \in \mathbb{R}^{2 \times 2}$ with $Mv = t$

$$\Leftrightarrow M \begin{pmatrix} 3 \\ -4 \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

Set $M = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$, then

$$M \begin{pmatrix} 3 \\ -4 \end{pmatrix} = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} 3 \\ -4 \end{pmatrix} = \begin{pmatrix} 3a - 4b \\ 3c - 4d \end{pmatrix}$$

We therefore want to solve $\begin{pmatrix} 3a - 4b \\ 3c - 4d \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$.

This is in fact a linear system

$$\frac{1}{3} \begin{cases} 3a - 4b & = 1 \\ 3c - 4d & = 2 \end{cases}$$

$$\Leftrightarrow \begin{cases} \underline{a} - \frac{4}{3}\underline{b} & = \frac{1}{3} \\ \underline{c} - \frac{4}{3}\underline{d} & = \frac{2}{3} \end{cases}$$

free

Pivot

Solutions:

$$a = \frac{1}{3} + \frac{4}{3}t_1, \quad c = \frac{2}{3} + \frac{4}{3}t_2$$
$$b = t_1, \quad d = t_2$$

All matrices of the form

$$M = \begin{pmatrix} \frac{1}{3} + \frac{4}{3}t_1 & t_1 \\ \frac{2}{3} + \frac{4}{3}t_2 & t_2 \end{pmatrix}$$

for any $t_1, t_2 \in \mathbb{R}$ satisfy $Mv = t$.

In particular, such a matrix is not unique.

Comments to Homework 2:

Exercise 1. (3+3 = 6 Points) Show that for all $A \in \mathbb{R}^{m \times n}$, $x, y \in \mathbb{R}^n$ and $\lambda \in \mathbb{R}$ we have

i) $A(x + y) = Ax + Ay$,

ii) $A(\lambda x) = \lambda(Ax)$.

Write $x = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix}$, $y = \begin{pmatrix} y_1 \\ \vdots \\ y_n \end{pmatrix}$ and $A = \begin{pmatrix} a_{11} & \dots & a_{1n} \\ \vdots & & \vdots \\ a_{m1} & \dots & a_{mn} \end{pmatrix}$

and then calculate both sides

$$A(x+y) = A \begin{pmatrix} x_1 + y_1 \\ \vdots \\ x_n + y_n \end{pmatrix} = \dots$$

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$$Ax + Ay = \dots = \dots$$

Exercise 2. (2+1+3 = 6 Points) Let $p(x) = a_0 + a_1x + a_2x^2 + a_3x^3$ be a polynomial of degree 3 with real coefficients $a_0, a_1, a_2, a_3 \in \mathbb{R}$. For such a polynomial p define the vector v_p by

$$v_p = \begin{pmatrix} a_0 \\ a_1 \\ a_2 \\ a_3 \end{pmatrix} \in \mathbb{R}^4.$$

- (i) Find a matrix $D \in \mathbb{R}^{4 \times 4}$, such that $v_q = Dv_p$, where $q(x) = 2p(x) - p'(x)$.
(Here p' denotes the derivative of the polynomial p with respect to x).
- (ii) Determine the rank of D in (i).
- (iii) For an arbitrary polynomial p of degree 3, find a polynomial s , such that $v_p = Dv_s$.

Example: $p(x) = 1 + 2x - 3x^2 + 5x^3$ then

$$v_p = \begin{pmatrix} 1 \\ 2 \\ -3 \\ 5 \end{pmatrix}$$

(i): • calculate $2p(x) - p'(x)$
for $p(x) = a_0 + a_1x + a_2x^2 + a_3x^3$

(ii) calculate $\text{rref}(D)$

(iii) Solve linear system.

Exercise 3. (2+2 = 4 Points) Let $A \in \mathbb{R}^{3 \times 3}$ be a matrix.

- (i) Show that if $\text{rk}(A) = 3$ then there exists just one vector $x \in \mathbb{R}^3$ with $Ax = 0$.
- (ii) Show that if $\text{rk}(A) \leq 2$ then there exist infinitely many vectors $x \in \mathbb{R}^3$ with $Ax = 0$.

If $A \in \mathbb{R}^{3 \times 3}$ how can $\text{rref}(A | \begin{smallmatrix} 0 \\ 0 \\ 0 \end{smallmatrix})$ look like if $\text{rk}(A) = 3$ and $\text{rk}(A) = 2$? What does this say about the solutions of $Ax = 0$?

Exercise 4. (4+2 = 6 Points) Let $a, b, c, d \in \mathbb{R}$ and $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$.

- (i) Show that $\text{rk}(A) = 2$ if and only if $ad - bc \neq 0$.
- (ii) We define the following subset of \mathbb{R}^2

$$L = \{x \in \mathbb{R}^2 \mid x = Av \text{ for some } v \in \mathbb{R}^2\}.$$

How does L look like if $\text{rk}(A) = 1$? How does it look like if $\text{rk}(A) = 2$?

Show two directions:

① $\text{rk}(A) = 2 \Rightarrow ad - bc \neq 0$

and ② $ad - bc \neq 0 \Rightarrow \text{rk}(A) = 2$

If P_1 and P_2 are statements then
 $P_1 \Rightarrow P_2$
 $(\Leftrightarrow) \neg P_2 \Rightarrow \neg P_1$
 \uparrow
negate

For ①: Show that if $ad - bc = 0$ then $\text{rk}(A) \neq 2$

For ②:

Try to bring $\begin{pmatrix} a & b \\ c & d \end{pmatrix}$ to rref. If $ad - bc \neq 0$ then you are allowed to divide by it.