

§ 11 Coordinates

From now on we will consider ordered bases.

This means we will write (b_1, \dots, b_n) for a basis $\{b_1, \dots, b_n\}$. The difference is that $\{b_1, b_2\} = \{b_2, b_1\}$ but $(b_1, b_2) \neq (b_2, b_1)$.

Definition 11.1 Let $B = (b_1, \dots, b_m)$ be a basis of $V \subset \mathbb{R}^n$.

We define the coordinate map by

$$C_B: \mathbb{R}^m \longrightarrow \mathbb{R}^n$$
$$\begin{pmatrix} \lambda_1 \\ \vdots \\ \lambda_m \end{pmatrix} \longmapsto \lambda_1 b_1 + \dots + \lambda_m b_m.$$

Theorem 11.2 Let $B = (b_1, \dots, b_m)$ be a basis of $V \subset \mathbb{R}^n$.

i) $C_B: \mathbb{R}^m \longrightarrow V$ is bijective.

ii) For all $x \in V$ there exist unique $\lambda_1, \dots, \lambda_m \in \mathbb{R}$ with

$(\forall x \in V \exists! \lambda_1, \dots, \lambda_m \in \mathbb{R}) \quad x = \lambda_1 b_1 + \dots + \lambda_m b_m.$

Proof: i) Since $\text{im } C_B = \text{span}\{b_1, \dots, b_m\} = V$
the map $C_B: \mathbb{R}^m \rightarrow V$ is surjective.

$$\begin{pmatrix} \lambda_1 \\ \vdots \\ \lambda_m \end{pmatrix} = \lambda \in \text{Ker } C_B \Leftrightarrow \lambda_1 b_1 + \dots + \lambda_m b_m = 0$$

$$\begin{aligned} &\Rightarrow \lambda = 0 \Rightarrow \text{Ker } C_B = \{0\} \\ &\quad \uparrow \\ &b_1, \dots, b_m \text{ lin. indep. } \Leftrightarrow C_B \text{ injective} \end{aligned}$$

Thm. 8.7.

$\Rightarrow C_B$ bijective.

ii) This is just a reformulation of i).

Definition 11.3 Let $\mathcal{B} = (b_1, \dots, b_m)$ be a basis of $V \subset \mathbb{R}^n$
and $x \in V$ with $x = \lambda_1 b_1 + \dots + \lambda_m b_m$.

i) The number $\lambda_1, \dots, \lambda_m \in \mathbb{R}$ are the coordinates of x
(in the basis \mathcal{B}).

ii) The coordinate vector of x is

$$[x]_{\mathcal{B}} = C_B^{-1}(x) = \begin{pmatrix} \lambda_1 \\ \vdots \\ \lambda_m \end{pmatrix}.$$

Example 37 1) $B = (e_1, \dots, e_n)$ is a basis of \mathbb{R}^n .

For all $x \in \mathbb{R}^n$ we have $[x]_B = x$.

2) Consider $b_1 = \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}$ and $b_2 = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}$.

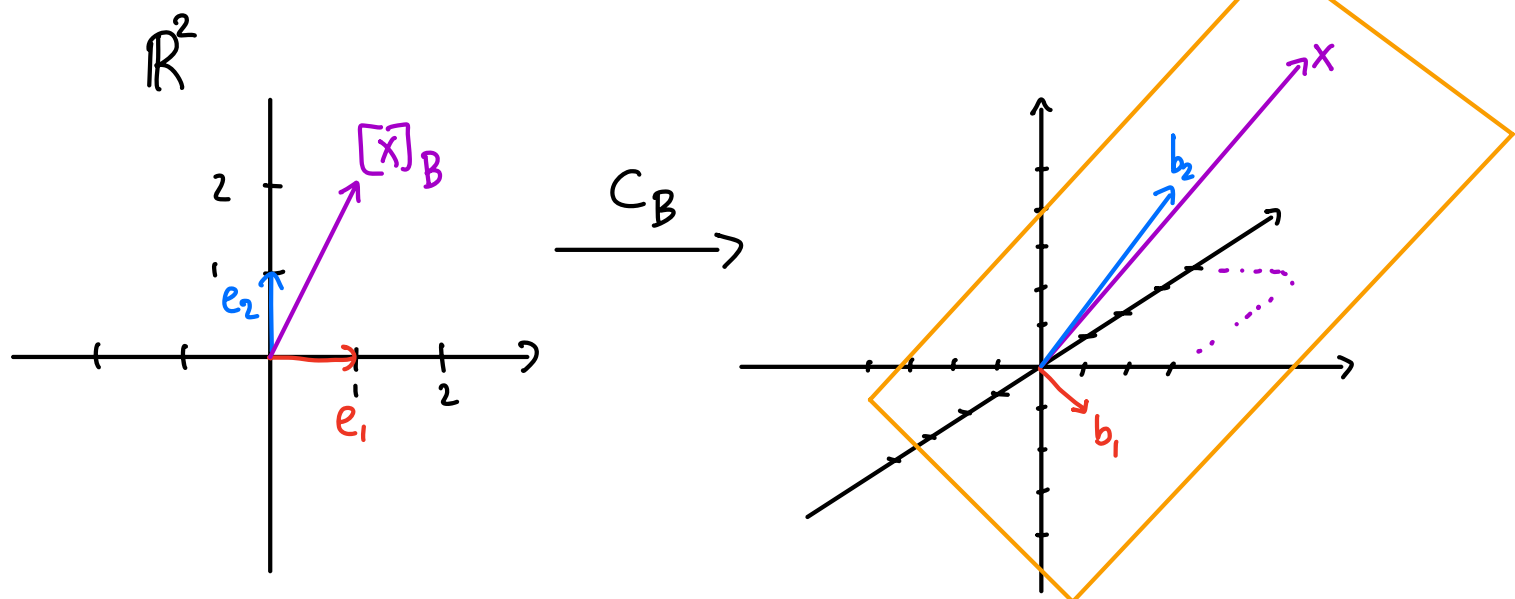
$B = (b_1, b_2)$ is a basis of $V = \text{span}\{b_1, b_2\}$.

Is $x = \begin{pmatrix} 3 \\ 4 \\ 5 \end{pmatrix} \in V$? What is $[x]_B$?

We need to solve $\lambda_1 b_1 + \lambda_2 b_2 = x$.

$$\begin{aligned} \sim \begin{matrix} & b_1 & b_2 & x \\ \textcircled{1} & \left(\begin{array}{cc|c} 1 & 1 & 3 \\ 0 & 2 & 4 \\ -1 & 3 & 5 \end{array} \right) & \sim & \begin{matrix} \textcircled{\frac{1}{2}} & \textcircled{-2} \\ \textcircled{4} \end{matrix} & \left(\begin{array}{cc|c} 1 & 1 & 3 \\ 0 & 2 & 4 \\ 0 & 4 & 8 \end{array} \right) & \sim & \begin{matrix} \textcircled{1} \\ \textcircled{-1} \end{matrix} & \left(\begin{array}{cc|c} 1 & 1 & 3 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{array} \right) \\ & & & & & & \sim & \left(\begin{array}{cc|c} 1 & 0 & 1 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{array} \right). \end{matrix} \end{aligned}$$

$$\Rightarrow x = 1 \cdot b_1 + 2 \cdot b_2 \Rightarrow [x]_B = \begin{pmatrix} 1 \\ 2 \end{pmatrix}.$$



Proposition 11.4 Let $\mathcal{B} = (b_1, \dots, b_m)$ be a basis of $V \subset \mathbb{R}^n$,

$x, y \in V$, $\mu \in \mathbb{R}$, then

- i) $[x+y]_{\mathcal{B}} = [x]_{\mathcal{B}} + [y]_{\mathcal{B}}$,
- ii) $[\mu x]_{\mathcal{B}} = \mu [x]_{\mathcal{B}}$,
- iii) $[0]_{\mathcal{B}} = 0$.

Proof: $[x]_{\mathcal{B}} = C_{\mathcal{B}}^{-1}(x)$. $C_{\mathcal{B}}$ is linear $\Rightarrow C_{\mathcal{B}}^{-1}$ linear.

All properties follow from the linearity of $C_{\mathcal{B}}^{-1}$. \square

Definition 11.5 Let $\mathcal{B} = (b_1, \dots, b_n)$ be a basis of \mathbb{R}^n .

The change-of-basis matrix associated with \mathcal{B} is

$$S_{\mathcal{B}} = [C_{\mathcal{B}}] = \begin{pmatrix} | & & | \\ b_1 & \dots & b_n \\ | & & | \end{pmatrix} \in \mathbb{R}^{n \times n}.$$

Remark: • $S_{\mathcal{B}}$ is invertible.

• For all $x \in \mathbb{R}^n$:
$$S_{\mathcal{B}} [x]_{\mathcal{B}} = C_{\mathcal{B}}([x]_{\mathcal{B}}) \\ = C_{\mathcal{B}}(C_{\mathcal{B}}^{-1}(x)) = x.$$

Definition 11.6 Let $F: \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear map,
 B_1 basis of \mathbb{R}^n , B_2 basis of \mathbb{R}^m .

The matrix of F with respect to B_1 and B_2 is

$$[F]_{B_1}^{B_2} = [C_{B_2}^{-1} \circ F \circ C_{B_1}].$$

In the case $n=m$ and $B_1=B_2$ we write $[F]_{B_1} = [F]_{B_1}^{B_1}$.

$$\begin{array}{ccc} \mathbb{R}^n & \xrightarrow{F} & \mathbb{R}^m \\ C_{B_1} \uparrow & & C_{B_2} \uparrow \downarrow C_B^{-1} \\ \mathbb{R}^n & \xrightarrow{C_B^{-1} \circ F \circ C_{B_1}} & \mathbb{R}^m \end{array}$$

Proposition 11.7 Let $F: \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear map,
 B_1 basis of \mathbb{R}^n , B_2 basis of \mathbb{R}^m .

i) We have $[F]_{B_1}^{B_2} = S_{B_2}^{-1} [F] S_{B_1}$.

ii) If $B_1 = (b_1, \dots, b_n)$ then

$$[F]_{B_1}^{B_2} = \begin{pmatrix} | & & | \\ [F(b_1)]_{B_2} & \dots & [F(b_n)]_{B_2} \\ | & & | \end{pmatrix}.$$

Proof: i) $[F]_{B_2}^{B_1} = [C_{B_2}^{-1} \circ F \circ C_{B_1}] = [C_{B_2}^{-1}] [F] [C_{B_1}]$
 $= S_{B_2}^{-1} [F] S_{B_1}.$

ii) The i -th column of $[F]_{B_2}^{B_1}$ is

$$[F]_{B_2}^{B_1} e_i = C_{B_2}^{-1} (F(C_{B_1}(e_i))) = C_{B_2}^{-1} (F(b_i))$$

$$= [F(b_i)]_{B_2} \quad \square$$

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1) $F: \mathbb{R}^n \rightarrow \mathbb{R}^m$, $B_1 = (e_1, \dots, e_n)$ $[C_{B_1}] = I_n$
 $B_2 = (e_1, \dots, e_m)$ $[C_{B_2}] = I_m$

Then $[F]_{B_2}^{B_1} = [F]$

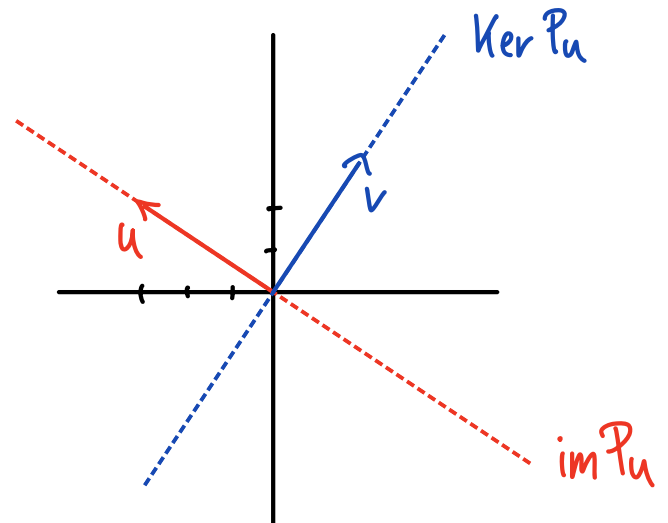
2) $P_u: \mathbb{R}^2 \rightarrow \mathbb{R}^2$, $u = \begin{pmatrix} -3 \\ 2 \end{pmatrix}$

$$\text{Ker } P_u = \{x \in \mathbb{R}^2 \mid u \cdot x = 0\}$$

$$= \text{span} \left\{ \begin{pmatrix} 2 \\ 3 \end{pmatrix} \right\}$$

\downarrow
 \checkmark

$\text{im } P_u = \text{span} \{u\}.$



u and v are linearly indep. $\Rightarrow B = (u, v)$ is a basis of \mathbb{R}^2 .

We have $P_u(u) = u$ and $P_u(v) = 0$, i.e.

$$[P_u]_B = [P_u]_B^B = \begin{pmatrix} [P_u(u)]_B & [P_u(v)]_B \\ | & | \\ 1 & 0 \\ 0 & 0 \end{pmatrix}.$$

Change-of-basis matrix:

$$S_B = \begin{pmatrix} | & | \\ u & v \\ | & | \end{pmatrix} = \begin{pmatrix} -3 & 2 \\ 2 & 3 \end{pmatrix}.$$

Inverse: $S_B^{-1} = \begin{pmatrix} -\frac{3}{13} & \frac{2}{13} \\ \frac{2}{13} & \frac{3}{13} \end{pmatrix}$ (check!)

By Prop 11.7 we have $[P_u]_B = [P_u]_B^B = S_B^{-1} [P_u] S_B$

$$\begin{aligned} \Rightarrow [\bar{F}] &= S_B [P_u]_B S_B^{-1} = \begin{pmatrix} -3 & 2 \\ 2 & 3 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} -\frac{3}{13} & \frac{2}{13} \\ \frac{2}{13} & \frac{3}{13} \end{pmatrix} \\ &= \begin{pmatrix} \frac{9}{13} & -\frac{6}{13} \\ -\frac{6}{13} & \frac{4}{13} \end{pmatrix}. \end{aligned}$$

You can check that this gives the same matrix you calculated in HW4 Ex 1(ii).

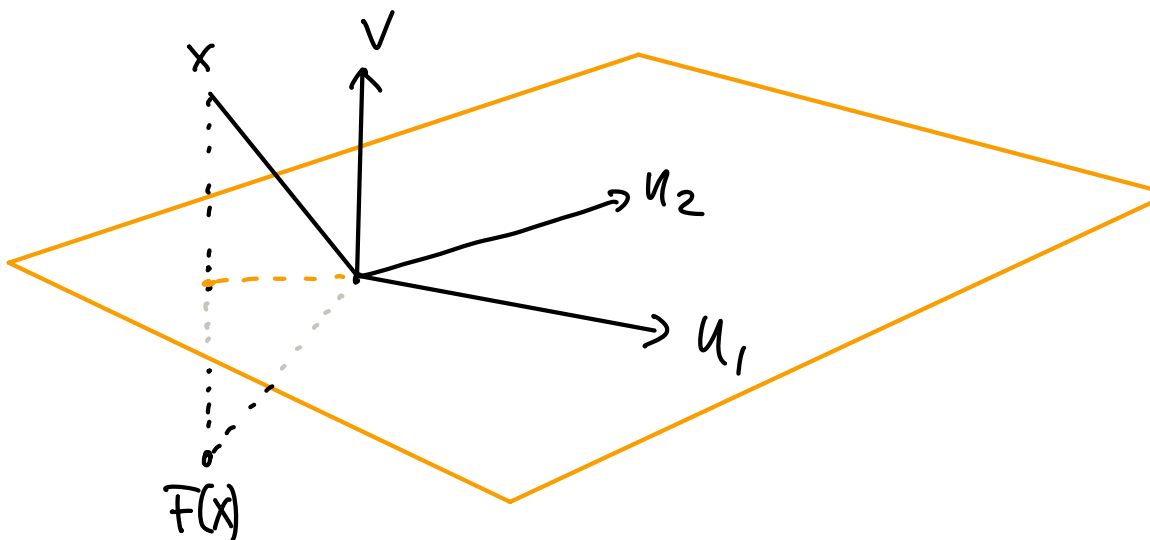
3) Let $F: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ be the reflection in the plane $U = \text{span} \left\{ \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} \right\}$.

Goal: Determine the matrix of $[F]$.

Idea: • Find "good" basis \mathcal{B} , where we can write down $[F]_{\mathcal{B}}$ directly.

• For this try to find $v \in \mathbb{R}^3$ which is orthogonal to u_1, u_2 and set $\mathcal{B} = (u_1, u_2, v)$.

(Notice: u_1, u_2 are lin. indep.)



To find $v = \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix} \in \mathbb{R}^3$ with $v \cdot u_1 = v \cdot u_2 = 0$ we need to solve
$$\begin{cases} v_1 + v_2 = 0 \\ v_2 + v_3 = 0 \end{cases}$$

$$\leadsto \begin{pmatrix} 1 & 1 & 0 & | & 0 \\ 0 & 1 & 1 & | & 0 \end{pmatrix} \sim \begin{pmatrix} 1 & 0 & -1 & | & 0 \\ 0 & 1 & 1 & | & 0 \end{pmatrix}$$

\Rightarrow all solutions are given by $t \cdot \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix}$.
We choose $t=1$, i.e. set

$$v = \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix}.$$

Check: u_1, u_2, v are linearly independent

$\Rightarrow B = (u_1, u_2, v)$ is a basis of \mathbb{R}^3 .

$$\begin{aligned} \text{We have } F(u_1) &= u_1 &\Rightarrow [F(u_1)]_B &= \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \\ F(u_2) &= u_2 &\Rightarrow [F(u_2)]_B &= \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \\ F(v) &= -v &\Rightarrow [F(v)]_B &= \begin{pmatrix} 0 \\ 0 \\ -1 \end{pmatrix} \end{aligned}$$

$$\Rightarrow [F]_B = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{pmatrix}.$$

Change-of-basis matrix:

$$S_B = \begin{pmatrix} | & | & | \\ u_1 & u_2 & v \\ | & | & | \end{pmatrix} = \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & -1 \\ 0 & 1 & 1 \end{pmatrix}$$

$$\text{check: } S_B^{-1} = \frac{1}{3} \begin{pmatrix} 2 & 1 & -1 \\ -1 & 1 & 2 \\ 1 & -1 & 1 \end{pmatrix}$$

$$\begin{aligned} \Rightarrow [F] &= S_B [F]_B S_B^{-1} = \begin{pmatrix} 1 & 0 & -1 \\ 1 & 0 & -1 \\ 0 & 1 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 \\ 1 & 0 & -1 \\ 0 & 1 & 1 \end{pmatrix} \frac{1}{3} \begin{pmatrix} 2 & 1 & -1 \\ -1 & 1 & 2 \\ 1 & -1 & 1 \end{pmatrix} \\ &= \frac{1}{3} \begin{pmatrix} 1 & 2 & -2 \\ 2 & 1 & 2 \\ -2 & 2 & 1 \end{pmatrix}. \end{aligned}$$