

1) (12 Points) Let $A = \begin{pmatrix} 1 & 0 & -1 \\ 2 & 1 & -3 \\ -2 & 0 & 1 \end{pmatrix}$ and $B = \begin{pmatrix} -1 & 0 & -1 \\ -4 & 1 & -1 \\ -3 & 1 & 0 \end{pmatrix}$.

- (i) Determine whether or not the matrices A, B are invertible and, if they are, compute their inverses.
- (ii) Calculate $C = BA$ and find all vectors $x \in \mathbb{R}^3$ with $Cx = x$.
- (iii) Give a basis for $\ker(A^n B)$ for all $n \geq 1$.

2) (14 Points) We define the subspace $U = \text{span}\{u_1, u_2, u_3, u_4\} \subset \mathbb{R}^3$, where

$$u_1 = \begin{pmatrix} 0 \\ -1 \\ 1 \end{pmatrix}, \quad u_2 = \begin{pmatrix} 0 \\ -3 \\ 3 \end{pmatrix}, \quad u_3 = \begin{pmatrix} -1 \\ 3 \\ 1 \end{pmatrix}, \quad u_4 = \begin{pmatrix} -1 \\ 5 \\ -1 \end{pmatrix}.$$

- (i) Determine a basis $B = (b_1, \dots, b_m)$ of U and calculate its dimension.
- (ii) Calculate the coordinate vectors $[u_1]_B, [u_2]_B, [u_3]_B$, and $[u_4]_B$, where B is the basis from (i).
- (iii) Determine an orthonormal basis $F = (f_1, \dots, f_m)$ of U .
- (iv) Calculate the orthogonal projection $P_U(b)$ of $b = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}$ and decide if b is an element in U .

3) (12 Points) Let $u, v \in \mathbb{R}^3$ be two arbitrary non-zero vectors. Which of the following sets are subspaces? Justify your answers.

- (i) $U_1 = \{x \in \mathbb{R}^3 \mid x \bullet u = u \bullet u\}$.
- (ii) $U_2 = \left\{ \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} \in \mathbb{R}^3 \mid x_1 - x_2 = 3x_3 + x_2 \text{ and } x_2 = x_1 - x_3 \right\}$.
- (iii) $U_3 = \{x \in \mathbb{R}^3 \mid x \neq u\}$.
- (iv) $U_4 = \text{span}\{u, v\} \cup \text{span}\{u + v, u - v\}$.

4) (12 Points) Assume we have the following data points

i	1	2	3
x_i	1	2	3
y_i	0	2	3

- (i) Find the line of best fit for the above data, i.e. find $a, b \in \mathbb{R}$ such that the function $l(x) = ax + b$ minimizes the sum of squares $\sum_{i=1}^3 (l(x_i) - y_i)^2$.
- (ii) We define the following linear map

$$F : \mathbb{R}^2 \longrightarrow \mathbb{R}^3$$

$$\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \longmapsto \begin{pmatrix} x_1 + x_2 \\ 2x_1 + x_2 \\ 3x_1 + x_2 \end{pmatrix}$$

and set $V = \text{im}(F)$. Determine the orthogonal projection $P_V(y)$ of $y = \begin{pmatrix} 0 \\ 2 \\ 3 \end{pmatrix}$ onto V .

- (iii) Give a basis B of V and determine $[P_V(y)]_B$, where V and y are the same as in (ii).

1) (12 Points) Let $A = \begin{pmatrix} 1 & 0 & -1 \\ 2 & 1 & -3 \\ -2 & 0 & 1 \end{pmatrix}$ and $B = \begin{pmatrix} -1 & 0 & -1 \\ -4 & 1 & -1 \\ -3 & 1 & 0 \end{pmatrix}$.

(i) Determine whether or not the matrices A , B are invertible and, if they are, compute their inverses.

(ii) Calculate $C = BA$ and find all vectors $x \in \mathbb{R}^3$ with $Cx = x$.

(iii) Give a basis for $\ker(A^n B)$ for all $n \geq 1$.

(i) We calculate $\text{rref}(A | I_3)$ and $\text{rref}(B | I_3)$:

$$(A | I_3) = \begin{array}{c} \textcircled{2} \textcircled{-2} \\ \begin{array}{l} \hookrightarrow \\ \hookrightarrow \end{array} \end{array} \left(\begin{array}{ccc|ccc} 1 & 0 & -1 & 1 & 0 & 0 \\ 2 & 1 & -3 & 0 & 1 & 0 \\ -2 & 0 & 1 & 0 & 0 & 1 \end{array} \right) \sim \begin{array}{c} \begin{array}{l} \uparrow \\ \uparrow \\ \ominus \ominus \ominus \end{array} \\ \begin{array}{l} \hookrightarrow \\ \hookrightarrow \end{array} \end{array} \left(\begin{array}{ccc|ccc} 1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & -1 & -2 & 1 & 0 \\ 0 & 0 & -1 & 2 & 0 & 1 \end{array} \right)$$

$$\sim \left(\begin{array}{ccc|ccc} 1 & 0 & 0 & -1 & 0 & -1 \\ 0 & 1 & 0 & -4 & 1 & -1 \\ 0 & 0 & 1 & -2 & 0 & -1 \end{array} \right) = (I_3 | A^{-1})$$

$\Rightarrow A$ is invertible with inverse $A^{-1} = \begin{pmatrix} -1 & 0 & -1 \\ -4 & 1 & -1 \\ -2 & 0 & -1 \end{pmatrix}$.

$$(B | I_3) = \begin{array}{c} \textcircled{1} \textcircled{-3} \textcircled{-4} \\ \begin{array}{l} \hookrightarrow \\ \hookrightarrow \end{array} \end{array} \left(\begin{array}{ccc|ccc} -1 & 0 & -1 & 1 & 0 & 0 \\ -4 & 1 & -1 & 0 & 1 & 0 \\ -3 & 1 & 0 & 0 & 0 & 1 \end{array} \right) \sim \begin{array}{c} \textcircled{-1} \\ \begin{array}{l} \hookrightarrow \\ \hookrightarrow \end{array} \end{array} \left(\begin{array}{ccc|ccc} 1 & 0 & 1 & -1 & 0 & 0 \\ 0 & 1 & 3 & -4 & 1 & 0 \\ 0 & 1 & 3 & 0 & -3 & 1 \end{array} \right)$$

$$\sim \begin{array}{c} \text{rref}(B) \\ \begin{array}{l} \sim \\ \sim \end{array} \end{array} \left(\begin{array}{ccc|ccc} 1 & 0 & 1 & -1 & 0 & 0 \\ 0 & 1 & 3 & -4 & 1 & 0 \\ 0 & 0 & 0 & 4 & -4 & 1 \end{array} \right)$$

$\Rightarrow B$ is not invertible since $\text{rref}(B) \neq \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$

(ii) We have

$$C = BA = \begin{pmatrix} -1 & 0 & -1 \\ -4 & 1 & -1 \\ -3 & 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 \\ 2 & 1 & -3 \\ -2 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -1 & 1 & 0 \end{pmatrix}.$$

Since $Cx = \tilde{I}_3 x$ is equivalent to $(C - I_3)x = 0$ we need to calculate $\ker(C - I_3)$.

$$C - I_3 = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ -1 & 1 & -1 \end{pmatrix} \sim \begin{pmatrix} 1 & -1 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \text{rref}(C - I_3)$$

\Rightarrow The solutions $x = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$ of $Cx = x$ are given by

$$x_1 = t_1 - t_2$$

$$x_2 = t_1 \quad \text{for } t_1, t_2 \in \mathbb{R}.$$

$$x_3 = t_2$$

(They are $\text{span}\left\{ \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} \right\}$).

(iii) Since A invertible $\Rightarrow A^n$ invertible $\forall n \geq 1$

$$\Rightarrow \text{Ker}(A^n) = \{0\}$$

we have that $A^n y = 0$ if and only if $y = 0$.

Therefore $A^n Bx = 0$ if and only if $Bx = 0$.

$$\Rightarrow \text{Ker}(A^n B) = \text{Ker}(B).$$

By (i) we have $\text{rref}(B) = \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 3 \\ 0 & 0 & 0 \end{pmatrix}$

and therefore the solutions of $Bx = 0$ with $x = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$

are
$$\begin{aligned} x_1 &= -t \\ x_2 &= -3t \\ x_3 &= t \end{aligned} \quad \text{for } t \in \mathbb{R}, \text{ i.e. } x = t \begin{pmatrix} -1 \\ -3 \\ 1 \end{pmatrix}.$$

$$\Rightarrow \text{Ker}(A^n B) = \text{Ker}(B) = \text{span} \left\{ \begin{pmatrix} -1 \\ -3 \\ 1 \end{pmatrix} \right\}$$

$$\Rightarrow \left(\begin{pmatrix} -1 \\ -3 \\ 1 \end{pmatrix} \right) \text{ is a basis of } \text{Ker}(A^n B) \forall n \geq 1,$$

2) (14 Points) We define the subspace $U = \text{span}\{u_1, u_2, u_3, u_4\} \subset \mathbb{R}^3$, where

$$u_1 = \begin{pmatrix} 0 \\ -1 \\ 1 \end{pmatrix}, \quad u_2 = \begin{pmatrix} 0 \\ -3 \\ 3 \end{pmatrix}, \quad u_3 = \begin{pmatrix} -1 \\ 3 \\ 1 \end{pmatrix}, \quad u_4 = \begin{pmatrix} -1 \\ 5 \\ -1 \end{pmatrix}.$$

- (i) Determine a basis $B = (b_1, \dots, b_m)$ of U and calculate its dimension.
- (ii) Calculate the coordinate vectors $[u_1]_B, [u_2]_B, [u_3]_B$, and $[u_4]_B$, where B is the basis from (i).
- (iii) Determine an orthonormal basis $F = (f_1, \dots, f_m)$ of U .
- (iv) Calculate the orthogonal projection $P_U(b)$ of $b = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}$ and decide if b is an element in U .

(i) We calculate $\text{rref}(u_1 \ u_2 \ u_3 \ u_4)$:

$$\begin{pmatrix} u_1 & u_2 & u_3 & u_4 \end{pmatrix} = \begin{array}{c} \rightarrow \\ \rightarrow \\ \rightarrow \\ \rightarrow \end{array} \begin{pmatrix} 0 & 0 & -1 & -1 \\ -1 & -3 & 3 & 5 \\ 1 & 3 & 1 & -1 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

$$\begin{array}{c} \rightarrow \\ \rightarrow \\ \rightarrow \\ \rightarrow \end{array} \begin{pmatrix} 1 & 3 & 1 & -1 \\ 0 & 0 & 4 & 4 \\ 0 & 0 & -1 & -1 \\ 0 & 0 & 0 & 0 \end{pmatrix} \sim \begin{pmatrix} 1 & 3 & 0 & -2 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

Columns with pivot elements.

$\Rightarrow B = (\overset{b_1}{\underbrace{u_1}}, \overset{b_2}{\underbrace{u_3}})$ is a basis of U .
 $\Rightarrow \dim(U) = 2$.

(ii) From (i) we get

$$[u_1]_B = \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \quad [u_2]_B = \begin{pmatrix} 3 \\ 0 \end{pmatrix}, \quad [u_3]_B = \begin{pmatrix} 0 \\ 1 \end{pmatrix}, \quad [u_4]_B = \begin{pmatrix} -2 \\ 1 \end{pmatrix}.$$

(iii) We use the GSA to construct (f_1, f_2)

from $(b_1, b_2) = (u_1, u_3)$:

$$f_1 = \frac{1}{\|b_1\|} b_1 = \frac{1}{\sqrt{2}} \begin{pmatrix} 0 \\ -1 \\ 1 \end{pmatrix} \quad f \cdot b_2 = \frac{1}{\sqrt{2}} \overbrace{\begin{pmatrix} 0 \\ -1 \\ 1 \end{pmatrix} \cdot \begin{pmatrix} -1 \\ 3 \\ 1 \end{pmatrix}}^{-2}$$

$$w_2 = b_2 - (f_1 \cdot b_2) f_1 = \begin{pmatrix} -1 \\ 3 \\ 1 \end{pmatrix} + \frac{2}{\sqrt{2}\sqrt{2}} \begin{pmatrix} 0 \\ -1 \\ 1 \end{pmatrix} = \begin{pmatrix} -1 \\ 2 \\ 2 \end{pmatrix}.$$

$$f_2 = \frac{1}{\|w_2\|} w_2 = \frac{1}{\sqrt{9}} \begin{pmatrix} -1 \\ 2 \\ 2 \end{pmatrix} = \frac{1}{3} \begin{pmatrix} -1 \\ 2 \\ 2 \end{pmatrix}.$$

(iv) Since (f_1, f_2) is an ONB of U , we

have $P_U(b) = (f_1 \cdot b) f_1 + (f_2 \cdot b) f_2$

$$\begin{aligned} &= \left(\frac{1}{\sqrt{2}} \overbrace{\begin{pmatrix} 0 \\ -1 \\ 1 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}}^1 \right) \frac{1}{\sqrt{2}} \begin{pmatrix} 0 \\ -1 \\ 1 \end{pmatrix} + \left(\frac{1}{3} \overbrace{\begin{pmatrix} -1 \\ 2 \\ 2 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}}^9 \right) \frac{1}{3} \begin{pmatrix} -1 \\ 2 \\ 2 \end{pmatrix} \\ &= \frac{1}{2} \begin{pmatrix} 0 \\ -1 \\ 1 \end{pmatrix} + \begin{pmatrix} -1 \\ 2 \\ 2 \end{pmatrix} = \begin{pmatrix} -1 \\ \frac{3}{2} \\ \frac{5}{2} \end{pmatrix} = \frac{1}{2} \begin{pmatrix} -2 \\ 3 \\ 5 \end{pmatrix}. \end{aligned}$$

Therefore $P_U(b) \neq b$ and thus $b \notin U$. (because $P_U(x) = x$ for all $x \in U$)

3) (12 Points) Let $u, v \in \mathbb{R}^3$ be two arbitrary non-zero vectors. Which of the following sets are subspaces? Justify your answers.

(i) $U_1 = \{x \in \mathbb{R}^3 \mid x \bullet u = u \bullet u\}$.

(ii) $U_2 = \left\{ \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} \in \mathbb{R}^3 \mid \underbrace{x_1 - x_2 = 3x_3 + x_2}_{x_1 - 2x_2 - 3x_3 = 0} \text{ and } \underbrace{x_2 = x_1 - x_3}_{x_1 - x_2 - x_3 = 0} \right\}$.

(iii) $U_3 = \{x \in \mathbb{R}^3 \mid x \neq u\}$.

(iv) $U_4 = \text{span}\{u, v\} \cup \text{span}\{u + v, u - v\}$.

(i) If $u \neq 0$ we have $u \bullet u \neq 0$. But since $0 \bullet u = 0$ we would get $0 \notin U_1 \Rightarrow U_1$ is not a subspace.

(ii) Define the linear map

$$F: \mathbb{R}^3 \rightarrow \mathbb{R}^2$$

$$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} \mapsto \begin{pmatrix} x_1 - 2x_2 - 3x_3 \\ x_1 - x_2 - x_3 \end{pmatrix} = \begin{pmatrix} 1 & -2 & -3 \\ 1 & -1 & -1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}.$$

Then $U_2 = \text{Ker}(F)$ and therefore U_2 is a subspace.

(iii) If $u \neq 0$ we have $\frac{1}{2}u \neq u$. Therefore $\frac{1}{2}u \in U_3$. But $2 \cdot (\frac{1}{2}u) = u \notin U_3$ and therefore U_3 is not a subspace.

(iv) Since $u = \frac{1}{2}(u+v) + \frac{1}{2}(u-v)$

$$v = \frac{1}{2}(u+v) - \frac{1}{2}(u-v)$$

we have $u, v \in \text{span}\{u+v, u-v\}$.

But also $u+v, u-v \in \text{span}\{u, v\}$

$$\Rightarrow \text{span}\{u, v\} = \text{span}\{u+v, u-v\}.$$

$$\Rightarrow U_{\mathbb{C}} = \text{span}\{u, v\} \Rightarrow U_{\mathbb{C}} \text{ is a subspace.}$$

4) (12 Points) Assume we have the following data points

i	1	2	3
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y_i	0	2	3

- (i) Find the line of best fit for the above data, i.e. find $a, b \in \mathbb{R}$ such that the function $l(x) = ax + b$ minimizes the sum of squares $\sum_{i=1}^3 (l(x_i) - y_i)^2$.
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$$\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \mapsto \begin{pmatrix} x_1 + x_2 \\ 2x_1 + x_2 \\ 3x_1 + x_2 \end{pmatrix}$$

and set $V = \text{im}(F)$. Determine the orthogonal projection $P_V(y)$ of $y = \begin{pmatrix} 0 \\ 2 \\ 3 \end{pmatrix}$ onto V .

- (iii) Give a basis B of V and determine $[P_V(y)]_B$, where V and y are the same as in (ii).

(The key in this Exercise is to understand that (i) solves (ii) & (iii))

(i) We need to find $\begin{pmatrix} a \\ b \end{pmatrix}$ such that $\|A \begin{pmatrix} a \\ b \end{pmatrix} - y\|$ is minimal, where

$$A = \begin{pmatrix} 1 & 1 \\ 2 & 1 \\ 3 & 1 \end{pmatrix} \quad \text{and} \quad y = \begin{pmatrix} 0 \\ 2 \\ 3 \end{pmatrix}.$$

For this we need to solve the normal equation

$$A^T A \begin{pmatrix} a \\ b \end{pmatrix} = A^T y.$$

We have

$$A^T A = \begin{pmatrix} 1 & 2 & 3 \\ 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 2 & 1 \\ 3 & 1 \end{pmatrix} = \begin{pmatrix} 14 & 6 \\ 6 & 3 \end{pmatrix}$$

$$\text{and} \quad A^T y = \begin{pmatrix} 1 & 2 & 3 \\ 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} 0 \\ 2 \\ 3 \end{pmatrix} = \begin{pmatrix} 13 \\ 5 \end{pmatrix}$$

$$\leadsto \text{Want to solve } \begin{pmatrix} 14 & 6 \\ 6 & 3 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} 13 \\ 5 \end{pmatrix}$$

$$\leadsto \frac{1}{6} \begin{pmatrix} 14 & 6 & | & 13 \\ 6 & 3 & | & 5 \end{pmatrix} \sim \begin{pmatrix} 14 & 6 & | & 13 \\ -14 & 1 & | & -\frac{4}{3} \end{pmatrix} \quad \begin{matrix} \frac{39}{3} \\ 13 \end{matrix} - \frac{\frac{35}{3}}{\frac{4}{6}} = \frac{4}{3}$$

$$\begin{matrix} \rightarrow \\ \rightarrow \end{matrix} \begin{pmatrix} 1 & \frac{1}{2} & | & \frac{4}{3} \\ 0 & -1 & | & \frac{4}{3} \end{pmatrix} \sim \begin{pmatrix} 1 & 0 & | & \frac{3}{2} \\ 0 & 1 & | & -\frac{4}{3} \end{pmatrix}$$

$$\Rightarrow a = \frac{3}{2} \quad \text{and} \quad b = -\frac{4}{3}$$

$$\text{Best fitting line: } l(x) = \frac{3}{2}x - \frac{4}{3}$$

(ii) Since $[F] = A$ from (i) we get

$$P_V(b) = A \begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ 2 & 1 \\ 3 & 1 \end{pmatrix} \begin{pmatrix} \frac{3}{2} \\ -\frac{4}{3} \end{pmatrix} = \begin{pmatrix} \frac{3}{2} - \frac{4}{3} \\ 3 - \frac{4}{3} \\ \frac{9}{2} - \frac{4}{3} \end{pmatrix}$$

$$\frac{9}{2} - \frac{4}{3} = \frac{19}{6}$$

$$3 - \frac{4}{3} = \frac{5}{3}$$

$$\frac{3}{2} - \frac{4}{3} = \frac{1}{6}$$

$$= \begin{pmatrix} \frac{1}{6} \\ \frac{5}{3} \\ \frac{19}{6} \end{pmatrix} = \frac{1}{6} \begin{pmatrix} 1 \\ 10 \\ 19 \end{pmatrix}$$

(iii) We can take $B = \left(\begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \right)$, since

$\begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}$ and $\begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$ are lin. independent and they span $\text{im}(T)$.

Since $P_V(b) = A \begin{pmatrix} a \\ b \end{pmatrix} = a \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} + b \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$

we have

$$\underline{\underline{[P_V(b)]_B}} = \begin{pmatrix} a \\ b \end{pmatrix} = \underline{\underline{\begin{pmatrix} \frac{3}{2} \\ -\frac{4}{3} \end{pmatrix}}}$$