

Linear algebra I -1-
Final exam

i) $A = \begin{pmatrix} 0 & 1 & -2 & 3 \\ 1 & -2 & 3 & -4 \\ -2 & 3 & -4 & 5 \end{pmatrix}, B = \begin{pmatrix} 2 & 1 & 1 \\ 3 & 2 & 1 \\ 2 & 1 & 2 \end{pmatrix}$

i) • AB is not defined.

• $BA = \begin{pmatrix} -1 & 3 & -5 & 7 \\ 0 & 2 & -4 & 6 \\ -3 & 6 & -9 & 12 \end{pmatrix}$.

ii) A is not invertible because it is not a square matrix.

$$(B | I_3) = \begin{array}{c} \xrightarrow{\oplus} \\ \xrightarrow{\ominus} \end{array} \begin{pmatrix} 2 & 1 & 1 & | & 1 & 0 & 0 \\ 3 & 2 & 1 & | & 0 & 1 & 0 \\ 2 & 1 & 2 & | & 0 & 0 & 1 \end{pmatrix} \sim \begin{array}{c} \xrightarrow{\ominus} \\ \xrightarrow{\ominus} \end{array} \begin{pmatrix} 1 & 1 & 0 & | & -1 & 1 & 0 \\ 2 & 1 & 1 & | & 1 & 0 & 0 \\ 2 & 1 & 2 & | & 0 & 0 & 1 \end{pmatrix}$$

$$\sim \begin{array}{c} \xrightarrow{\oplus} \\ \xrightarrow{\oplus} \end{array} \begin{pmatrix} 1 & 1 & 0 & | & -1 & 1 & 0 \\ 0 & -1 & 1 & | & 3 & -2 & 0 \\ 0 & -1 & 2 & | & 2 & -2 & 1 \end{pmatrix} \sim \begin{array}{c} \xrightarrow{\oplus} \\ \xrightarrow{\oplus} \end{array} \begin{pmatrix} 1 & 1 & 0 & | & -1 & 1 & 0 \\ 0 & 1 & -1 & | & -3 & 2 & 0 \\ 0 & 0 & 1 & | & -1 & 0 & 1 \end{pmatrix}$$

$$\sim \begin{array}{c} \xrightarrow{\oplus} \\ \xrightarrow{\oplus} \end{array} \begin{pmatrix} 1 & 1 & 0 & | & -1 & 1 & 0 \\ 0 & 1 & 0 & | & -4 & 2 & 1 \\ 0 & 0 & 1 & | & -1 & 0 & 1 \end{pmatrix} \sim \begin{pmatrix} 1 & 0 & 0 & | & 3 & -1 & -1 \\ 0 & 1 & 0 & | & -4 & 2 & 1 \\ 0 & 0 & 1 & | & -1 & 0 & 1 \end{pmatrix}$$

B is invertible with inverse $B^{-1} = \begin{pmatrix} 3 & -1 & -1 \\ -4 & 2 & 1 \\ -1 & 0 & 1 \end{pmatrix}$.

iii) Since B is invertible we have

$$\text{im}(B) = \mathbb{R}^3 \quad \text{and} \quad \text{ker}(B) = \{0\}.$$

2) $U = \text{span}\{u_1, u_2, u_3\}$

$u_1 = \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix}, u_2 = \begin{pmatrix} 1 \\ 0 \\ -3 \end{pmatrix}, u_3 = \begin{pmatrix} 1 \\ 2 \\ -1 \end{pmatrix}$

i) To determine a basis for U we calculate the rref of $(u_1 | u_2 | u_3)$:

$\begin{matrix} \rightarrow \\ \rightarrow \\ \rightarrow \end{matrix} \begin{pmatrix} 0 & 1 & 1 \\ 1 & 0 & 2 \\ 1 & -3 & -1 \end{pmatrix} \sim \begin{matrix} \textcircled{3} \\ \rightarrow \\ \rightarrow \end{matrix} \begin{pmatrix} 1 & 0 & 2 \\ 0 & 1 & 1 \\ 0 & -3 & -3 \end{pmatrix} \sim \begin{pmatrix} 1 & 0 & 2 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{pmatrix}$
pivot.

The first two columns contain pivot elements and therefore $B = (b_1, b_2)$ with $b_1 = u_1, b_2 = u_2$ is a basis of U and $\dim U = 2$.

ii) From the above rref we can read off:

$[u_1]_B = \begin{pmatrix} 1 \\ 0 \end{pmatrix}, [u_2]_B = \begin{pmatrix} 0 \\ 1 \end{pmatrix}, [u_3]_B = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$

iii) To calculate a basis for U^\perp we need to find all $x \in \mathbb{R}^3$ with $x \cdot b_1 = x \cdot b_2 = 0$. This is equivalent to finding the solutions of $\begin{pmatrix} -b_1 & - \\ -b_2 & - \end{pmatrix} x = \begin{pmatrix} 0 & 1 & 1 \\ 1 & 0 & -3 \end{pmatrix} x = 0$.

$\begin{matrix} \rightarrow \\ \rightarrow \end{matrix} \left(\begin{array}{ccc|c} 0 & 1 & 1 & 0 \\ 1 & 0 & -3 & 0 \end{array} \right) \sim \left(\begin{array}{ccc|c} 1 & 0 & -3 & 0 \\ 0 & 1 & 1 & 0 \end{array} \right)$. We have the solutions
 $X = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} \begin{matrix} x_1 = +3t \\ x_2 = -t \\ x_3 = t \end{matrix} \quad t \in \mathbb{R}$

$\Rightarrow X = t \cdot \begin{pmatrix} 3 \\ -1 \\ 1 \end{pmatrix} \Rightarrow \left(\begin{pmatrix} 3 \\ -1 \\ 1 \end{pmatrix} \right)$ is a basis for U^\perp
" $\text{span}\left\{ \begin{pmatrix} 3 \\ -1 \\ 1 \end{pmatrix} \right\}$.

iv)

We define $G: \mathbb{R}^2 \rightarrow \mathbb{R}^3$

$$\begin{pmatrix} \lambda_1 \\ \lambda_2 \end{pmatrix} \mapsto \lambda_1 b_1 + \lambda_2 b_2.$$

This is the coordinate map C_B for which we know that $\text{im}(G) = U$ and $\text{ker} G = \{0\}$.

v) Let $[G]$ be the matrix of G in iv), i.e. $[G] = \begin{pmatrix} 1 & 1 \\ b_1 & b_2 \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \\ 1 & -3 \end{pmatrix}$.

Then we know that $\text{im}([G]) = U$. On the other hand

$$\text{we have } U^\perp = (\text{im}([G]))^\perp = \text{ker } [G]^T.$$

Therefore if we define $H: \mathbb{R}^3 \rightarrow \mathbb{R}^2$

$$x = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} \mapsto [G]^T x = \begin{pmatrix} \cancel{x_1} \\ \cancel{x_2} \\ x_3 \end{pmatrix}$$

$$= \begin{pmatrix} 0 & 1 & 1 \\ 1 & 0 & -3 \end{pmatrix} x$$

then we have $\text{ker } H = U^\perp$, since $[H] = [G]^T$.

This question was removed and was not part of the exam.

It was: "Find a linear map $H: \mathbb{R}^3 \rightarrow \mathbb{R}^2$ with $\text{ker } H = U^\perp$."

3)

i) $U_1 = \left\{ \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \in \mathbb{R}^2 \mid x_1 + x_2 = x_1 x_2 \right\}$

This is not a subspace, because $\begin{pmatrix} 2 \\ 2 \end{pmatrix} \in U_1$,
but $\begin{pmatrix} 2 \\ 2 \end{pmatrix} + \begin{pmatrix} 2 \\ 2 \end{pmatrix} = \begin{pmatrix} 4 \\ 4 \end{pmatrix} \notin U_1$, since $4 + 4 \neq 4 \cdot 4$.

ii) $U_2 = \left\{ \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \in \mathbb{R}^2 \mid 2x_1 = x_1 + x_2 \right\}$.

Since $2x_1 = x_1 + x_2 \Leftrightarrow x_1 = x_2$ we have $U_2 = \text{span}\left\{ \begin{pmatrix} 1 \\ 1 \end{pmatrix} \right\}$
and therefore U_2 is a subspace.

iii) $U_3 = \text{span}\left\{ \begin{pmatrix} 2 \\ 2 \end{pmatrix} \right\} \cup \text{span}\left\{ \begin{pmatrix} 2 \\ 1 \end{pmatrix} \right\}$

We have $\begin{pmatrix} 2 \\ 2 \end{pmatrix} \in U_3$ and $\begin{pmatrix} 2 \\ 1 \end{pmatrix} \in U_3$, but $\begin{pmatrix} 2 \\ 2 \end{pmatrix} + \begin{pmatrix} 2 \\ 1 \end{pmatrix} = \begin{pmatrix} 4 \\ 3 \end{pmatrix}$
is not an element in U_3 , since it is not a multiple of $\begin{pmatrix} 2 \\ 2 \end{pmatrix}$
or a multiple of $\begin{pmatrix} 2 \\ 1 \end{pmatrix}$.

Therefore U_3 is not a subspace.

iv) $U_4 = U_2 \cap U_3$.

Since $U_2 = \text{span}\left\{ \begin{pmatrix} 1 \\ 1 \end{pmatrix} \right\} = \text{span}\left\{ \begin{pmatrix} 2 \\ 2 \end{pmatrix} \right\}$ we have $U_4 = U_2$.

Therefore U_2 is also a subspace.

This question was not part of the exam.
It was "check if $U_4 = U_2 \cap U_3$ is a subspace".

4)

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i) We first notice that $b_1 = \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}$, $b_2 = \begin{pmatrix} 2 \\ 3 \\ 1 \end{pmatrix}$ form a basis of $\text{im}(T)$, since they are linearly independent.

Using the Gram-Schmidt algorithm we get:

$$f_1 = \frac{1}{\|b_1\|} b_1 = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}.$$

$$w_2 = b_2 - (b_2 \circ f_1) f_1 = \begin{pmatrix} 2 \\ 3 \\ 1 \end{pmatrix} - \frac{1}{2} \cdot \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 3 \\ 6 \\ 3 \end{pmatrix} = \frac{3}{2} \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix}$$

$$f_2 = \frac{1}{\|w_2\|} w_2 = \frac{1}{\sqrt{6}} \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix}.$$

Then $F = (f_1, f_2)$ is an orthonormal basis of $\text{im}(T)$.

ii) (Since $f_2 = \frac{1}{\sqrt{6}} \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix}$ is a basisvektor, $v = \begin{pmatrix} 1 \\ t \\ 1 \end{pmatrix}$ can just be an element of $\text{im}(T)$ if $t=2$.)

Alternative: We try to solve $F(x) = v$:

$$\textcircled{1} \begin{array}{l} \hookrightarrow \left(\begin{array}{cc|c} 1 & 2 & 1 \\ 0 & 3 & t \\ -1 & 1 & 1 \end{array} \right) \sim \textcircled{1} \begin{array}{l} \hookrightarrow \left(\begin{array}{cc|c} 1 & 2 & 1 \\ 0 & 3 & t \\ 0 & 3 & 2 \end{array} \right) \sim \left(\begin{array}{cc|c} 1 & 2 & 1 \\ 0 & 3 & t \\ 0 & 0 & 2-t \end{array} \right) \end{array}$$

\Rightarrow This just has a solution for $t=2$.

For $t=2$ we have $v = \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix}$ and since $v = \sqrt{6} f_2 = \frac{\sqrt{6}}{\sqrt{6}} \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix}$

we get $[v]_F = \begin{pmatrix} 0 \\ \sqrt{6} \end{pmatrix}$.

iii) A $w \in \mathbb{R}^3$ with $[w]_F = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$ is given by

$$1 \cdot f_1 + 2 \cdot f_2 = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} + \frac{2}{\sqrt{6}} \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix} = \begin{pmatrix} \frac{1}{\sqrt{2}} + \frac{2}{\sqrt{6}} \\ \frac{4}{\sqrt{6}} \\ -\frac{1}{\sqrt{2}} + \frac{2}{\sqrt{6}} \end{pmatrix}$$

$$= \begin{pmatrix} \frac{\sqrt{3}+2}{\sqrt{6}} \\ \frac{4}{\sqrt{6}} \\ \frac{-\sqrt{3}+2}{\sqrt{6}} \end{pmatrix} = \frac{1}{\sqrt{6}} \begin{pmatrix} \sqrt{3}+2 \\ 4 \\ -\sqrt{3}+2 \end{pmatrix}.$$

iv) To find a $x \in \mathbb{R}^2$ such that $\|T(x) - b\|$ is minimal, we need to solve

$$A^T A x = A^T b, \text{ with } A = [T] = \begin{pmatrix} 1 & 2 \\ 0 & 3 \\ -1 & 1 \end{pmatrix}.$$

$$A^T A = \begin{pmatrix} 1 & 0 & -1 \\ 2 & 3 & 1 \end{pmatrix} \begin{pmatrix} 1 & 2 \\ 0 & 3 \\ -1 & 1 \end{pmatrix} = \begin{pmatrix} 2 & 1 \\ 1 & 14 \end{pmatrix}.$$

$$A^T b = \begin{pmatrix} 1 & 0 & -1 \\ 2 & 3 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 2 \\ 4 \end{pmatrix} = \begin{pmatrix} -3 \\ 12 \end{pmatrix}.$$

Need to solve $\begin{pmatrix} 2 & 1 \\ 1 & 14 \end{pmatrix} x = \begin{pmatrix} -3 \\ 12 \end{pmatrix}$

$$\begin{pmatrix} 2 & 1 & | & -3 \\ 1 & 14 & | & 12 \end{pmatrix} \sim \begin{pmatrix} 1 & 14 & | & 12 \\ 0 & -27 & | & -27 \end{pmatrix} \sim \begin{pmatrix} 1 & 14 & | & 12 \\ 0 & 1 & | & 1 \end{pmatrix}$$

$$\sim \begin{pmatrix} 1 & 0 & | & -2 \\ 0 & 1 & | & 1 \end{pmatrix}.$$

We get the solution $x = \begin{pmatrix} -2 \\ 1 \end{pmatrix}$,
i.e. $\|T \begin{pmatrix} -2 \\ 1 \end{pmatrix} - \begin{pmatrix} 1 \\ 2 \\ 4 \end{pmatrix}\|$ is minimal.